

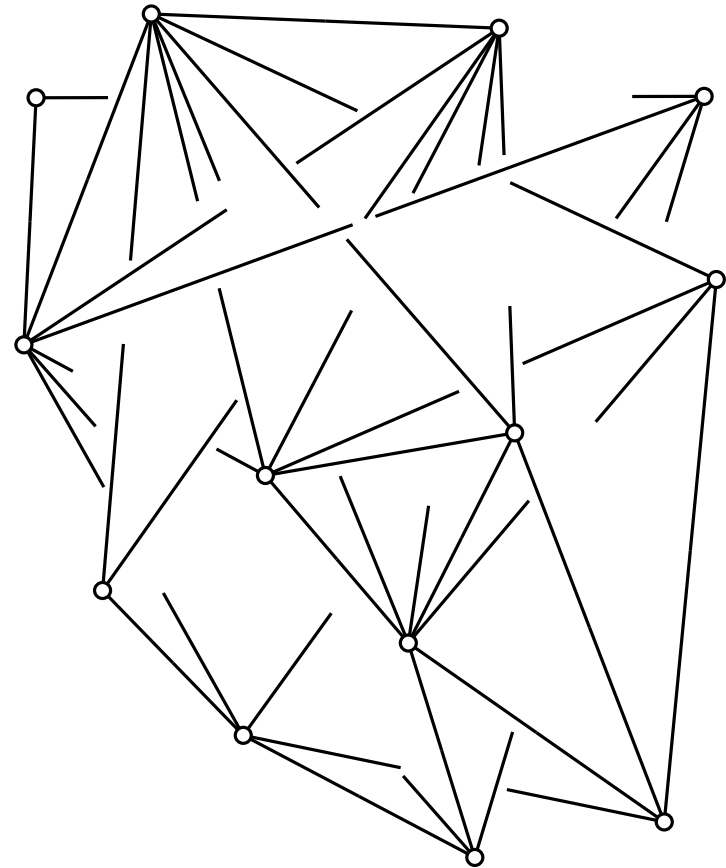
Maximizing Ink in Partial Edge Drawings of k -plane Graphs

Matthias Hummel, Fabian Klute,
Soeren Nickel, *Martin Nöllenburg*

GD 2019 · September 19, 2019



ALGORITHMS AND
COMPLEXITY GROUP



Partial Edge Drawings (PED)

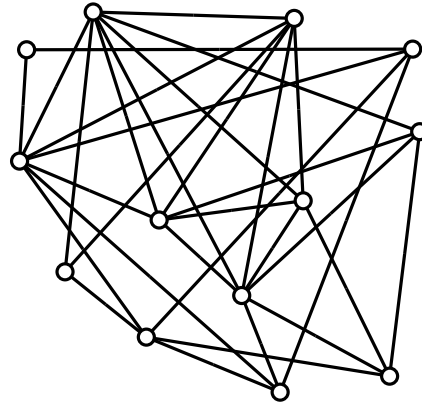
How to draw non-planar graphs?

Just *hide* the edge crossings!

[Becker et al. TVCG'95], [Bruckdorfer, Kaufmann FUN'12]

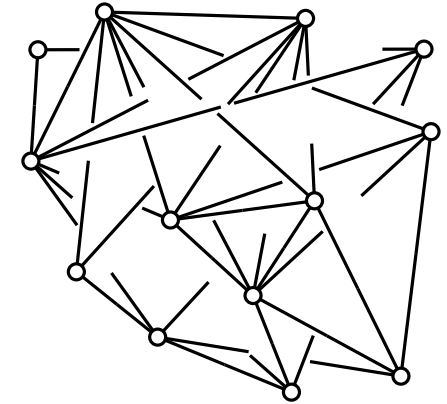
Input:

Straight-line
graph drawing
with crossings



Output:

“Crossing-free”
partial edge
drawing (PED)



Partial Edge Drawings (PED)

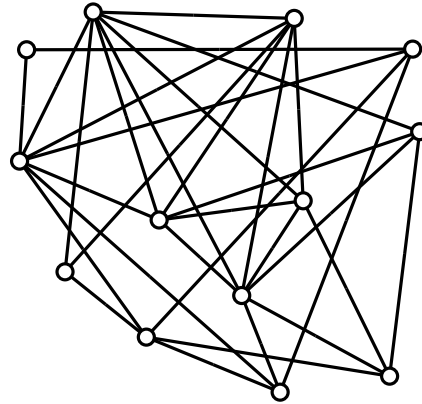
How to draw non-planar graphs?

Just *hide* the edge crossings!

[Becker et al. TVCG'95], [Bruckdorfer, Kaufmann FUN'12]

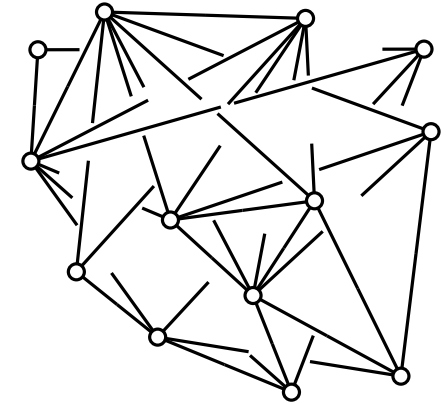
Input:

Straight-line graph drawing with crossings



Output:

“Crossing-free” partial edge drawing (PED)



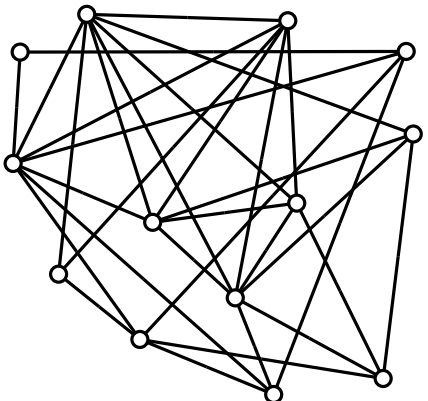
Properties:

- edges are drawn partially with middle part removed
- pairs of opposing **stubs**
- relies on closure and continuation principles in Gestalt theory
- user studies confirmed that PEDs reduce clutter and remain readable for long enough stubs

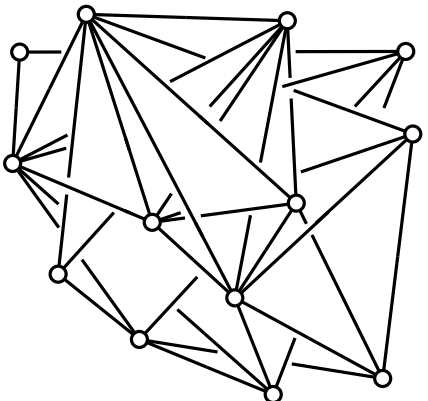


[Bruckdorfer et al. GD'15], [Burch et al. GD'11]

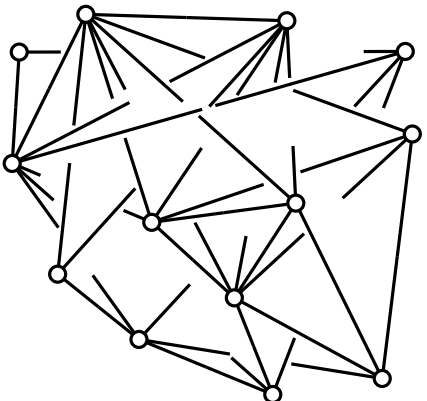
Symmetric Partial Edge Drawings (SPED)



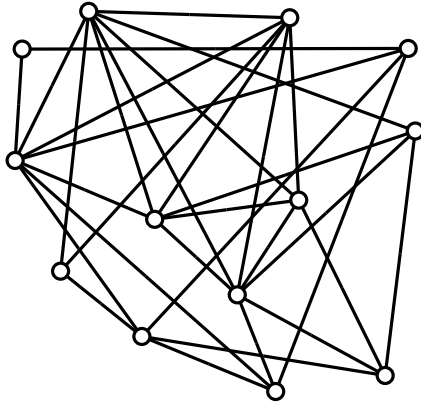
Input drawing



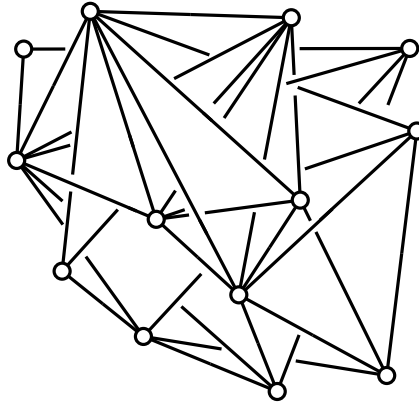
PED



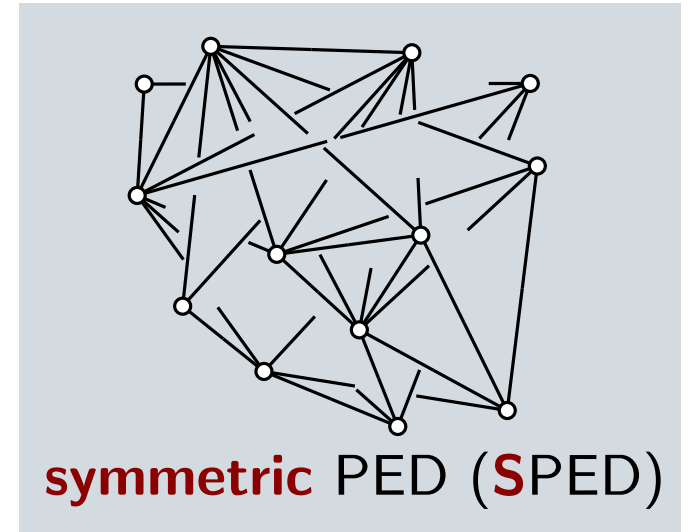
symmetric PED (**S**PED)



Input drawing



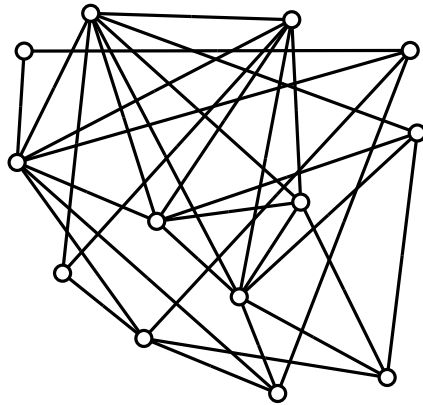
PED



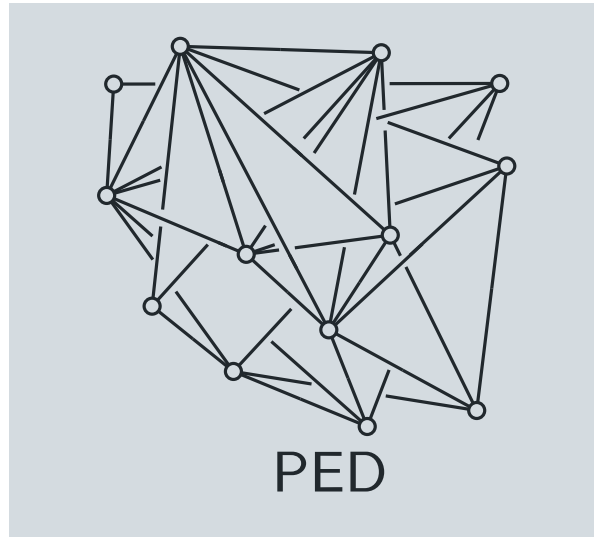
symmetric PED (**S**PED)

SPED:

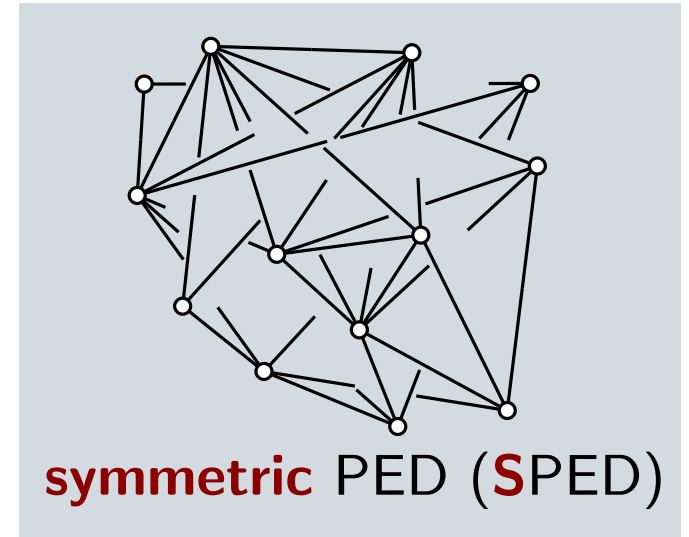
- both stubs of an edge have the same length
- identical stub lengths can facilitate finding adjacencies



Input drawing



PED



symmetric PED (**S**PED)

SPED:

- both stubs of an edge have the same length
- identical stub lengths can facilitate finding adjacencies

Optimization problem: maximize total stub length/drawn ink

→ **MaxPED** and **MaxSPED**

- show as much information as possible without crossings

Overview of Results

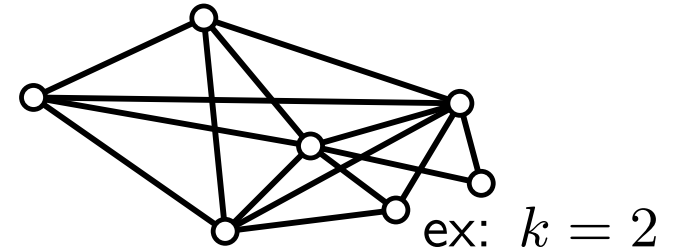
Given: k -plane^{*} straight-line drawing Γ

Find: maximum-ink (S)PED of Γ

Overview of Results

Given: k -plane^{*} straight-line drawing Γ

Find: maximum-ink (S)PED of Γ

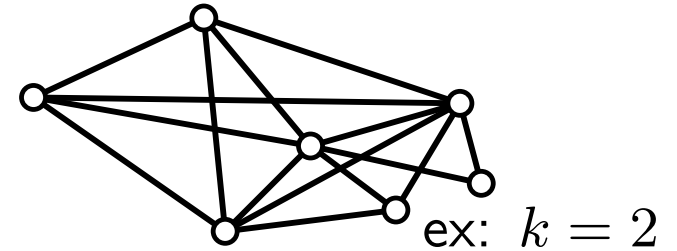


^{*}: k -plane drawing: every edge crossed by at most k other edges

Overview of Results

Given: k -plane^{*} straight-line drawing Γ

Find: maximum-ink (S)PED of Γ



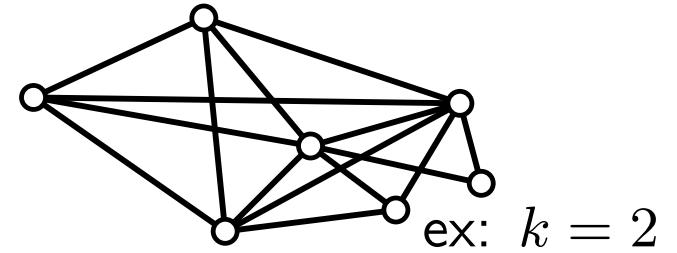
^{*}: k -plane drawing: every edge crossed by at most k other edges

	$k = 2$	$k = 3$	$k \geq 4$	arbitrary k
MaxSPED				NP-hard [Bruckdorfer PhD'15]
MaxPED	$O(n \log n)$ [Bruckdorfer et al. JGAA'17]			

Overview of Results

Given: k -plane* straight-line drawing Γ

Find: maximum-ink (S)PED of Γ



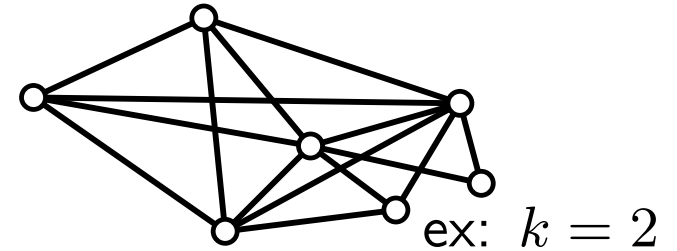
*: k -plane drawing: every edge crossed by at most k other edges

	$k = 2$	$k = 3$	$k \geq 4$	arbitrary k
MaxSPED		NP-hard		NP-hard [Bruckdorfer PhD'15]
MaxPED	$O(n \log n)$ [Bruckdorfer et al. JGAA'17]		NP-hard	

Overview of Results

Given: k -plane* straight-line drawing Γ

Find: maximum-ink (S)PED of Γ



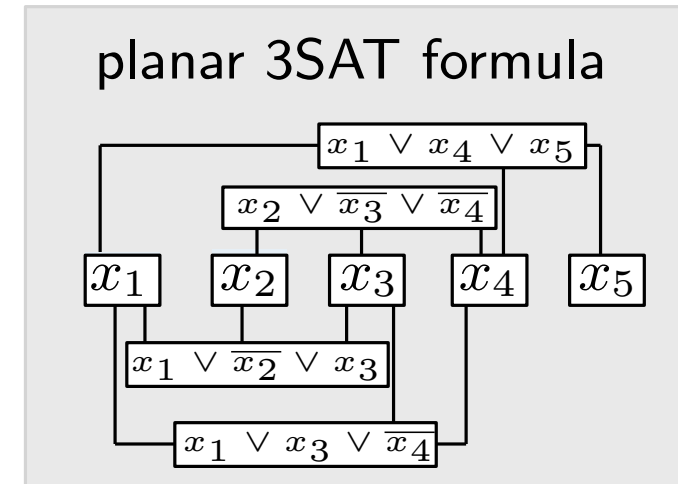
*: k -plane drawing: every edge crossed by at most k other edges

	$k = 2$	$k = 3$	$k \geq 4$	arbitrary k
MaxSPED		NP-hard		NP-hard [Bruckdorfer PhD'15]
MaxPED	$O(n \log n)$ [Bruckdorfer et al. JGAA'17]	Dynamic Programming if edge intersection graph <ul style="list-style-type: none"> is a tree, or more generally has bounded treewidth 		
			NP-hard	

NP-Hardness

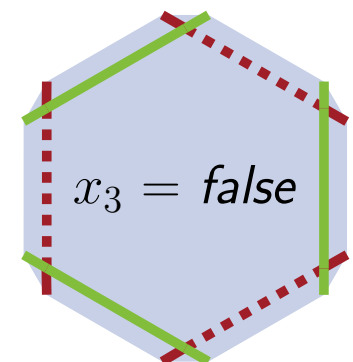
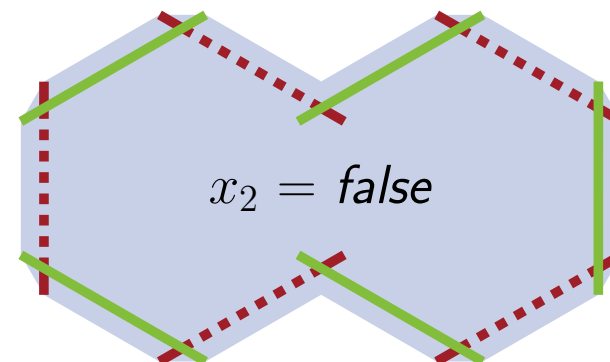
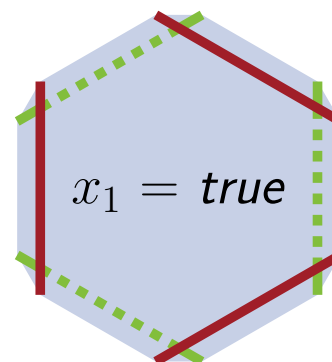
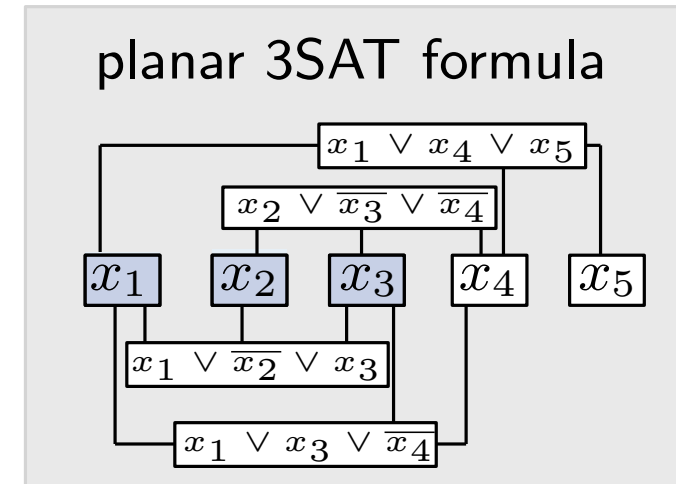
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction



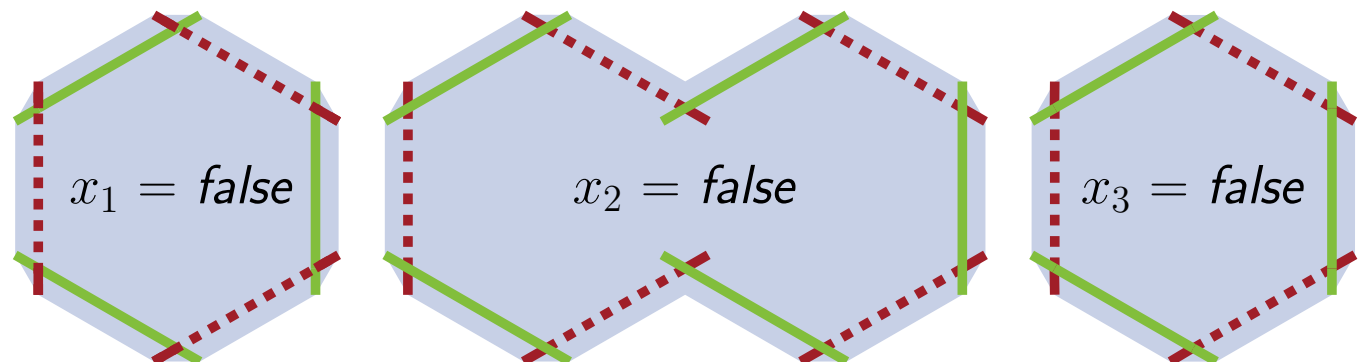
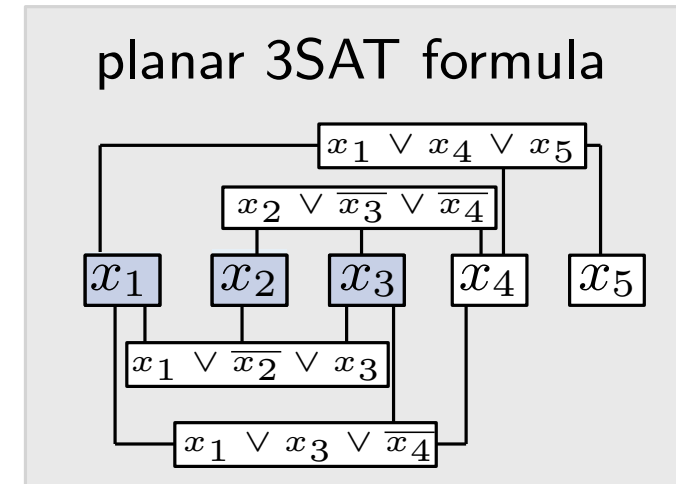
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states



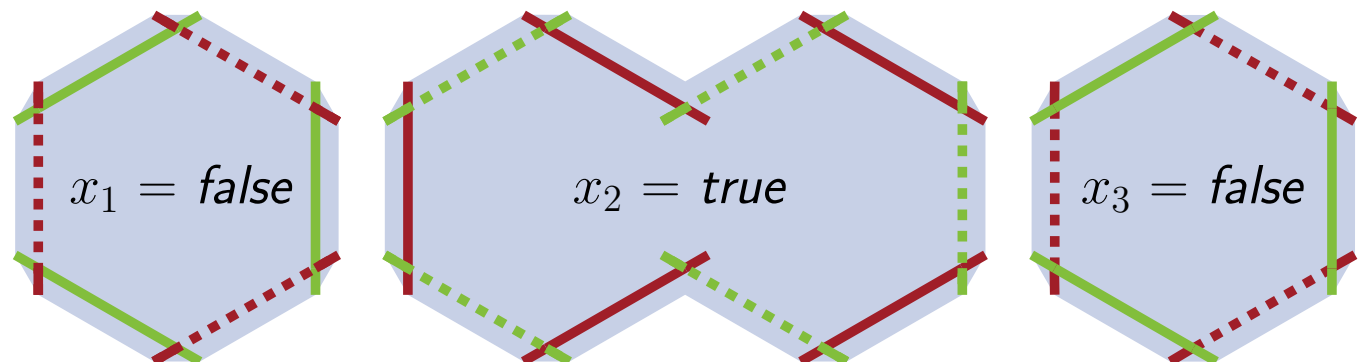
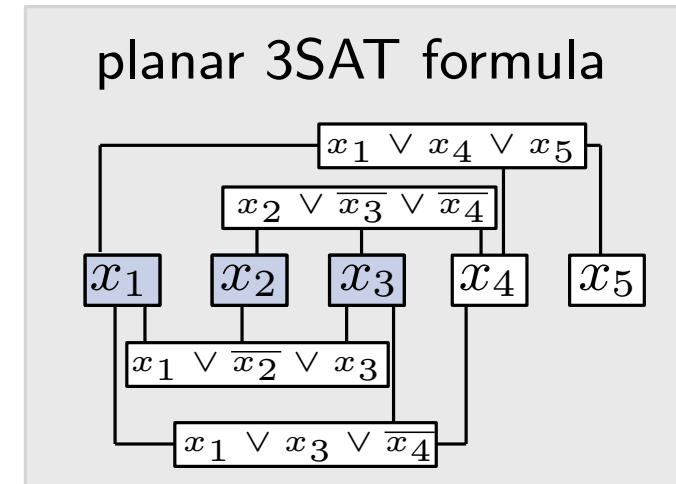
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states



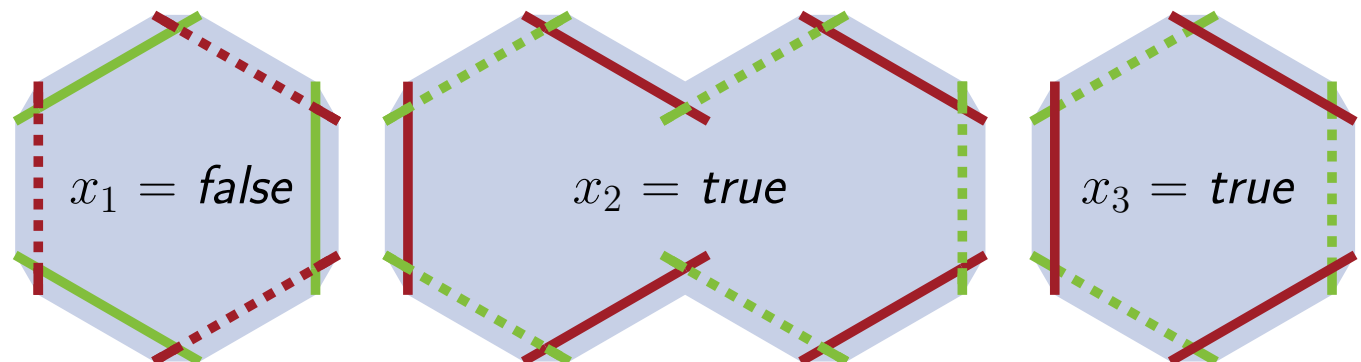
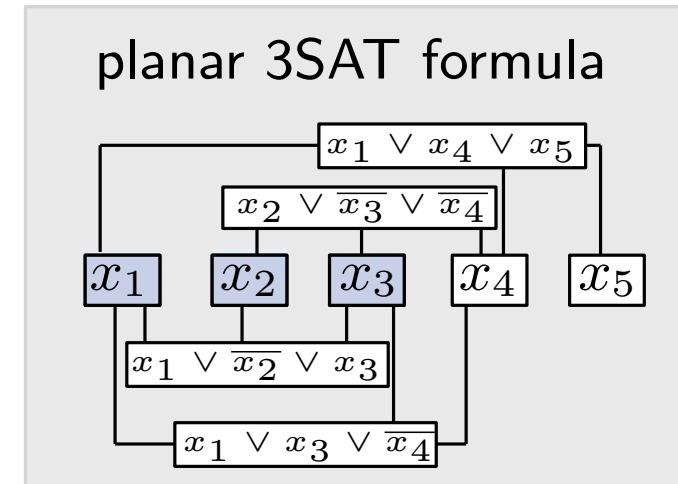
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states



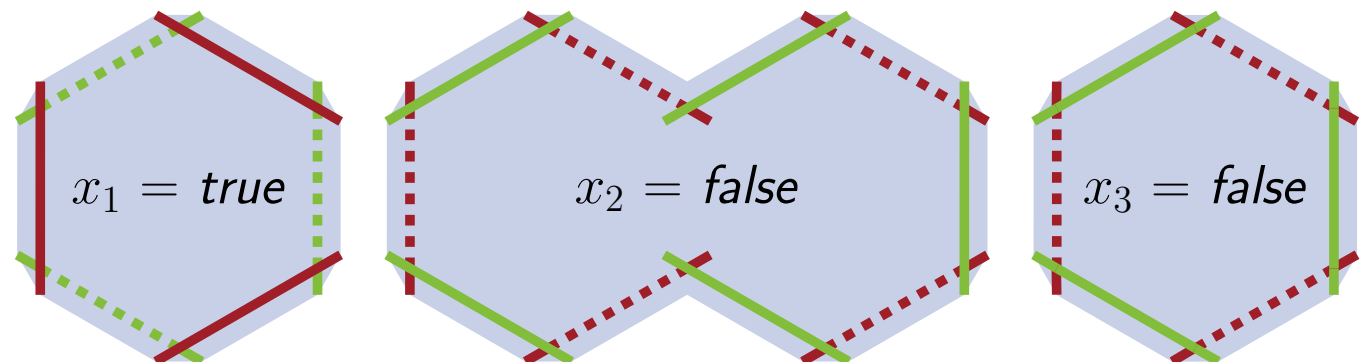
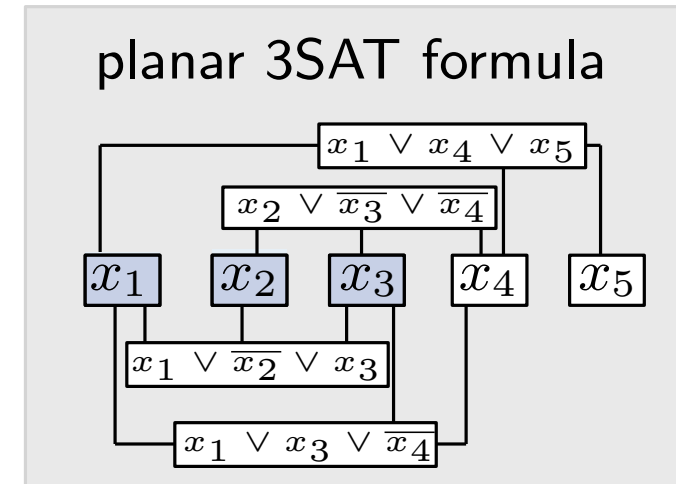
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states



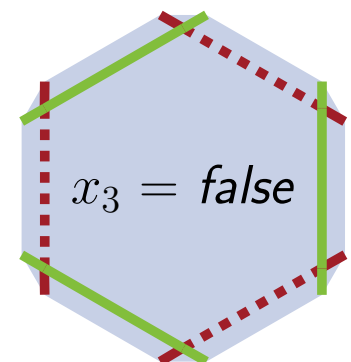
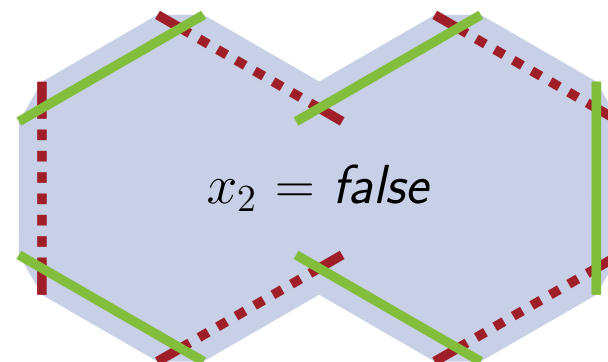
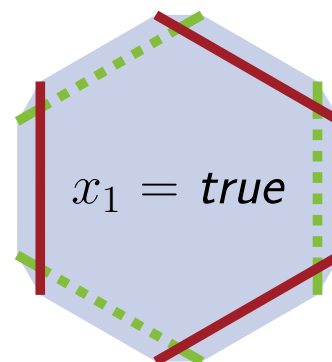
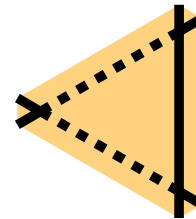
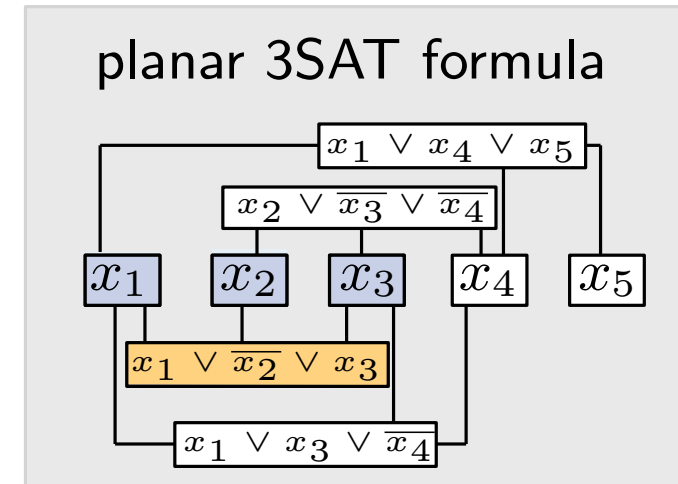
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states



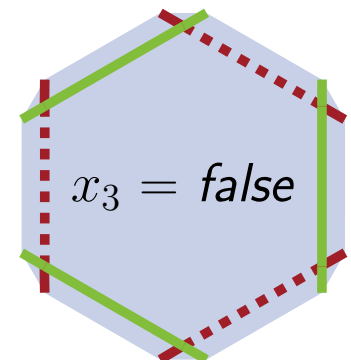
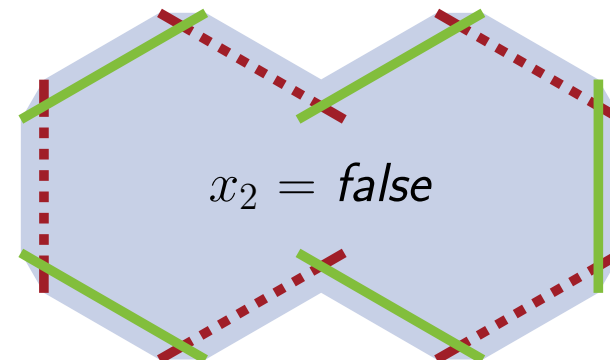
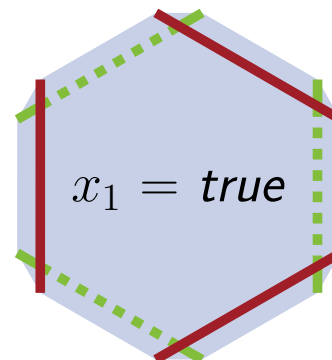
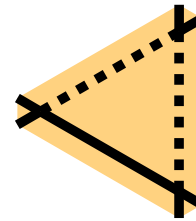
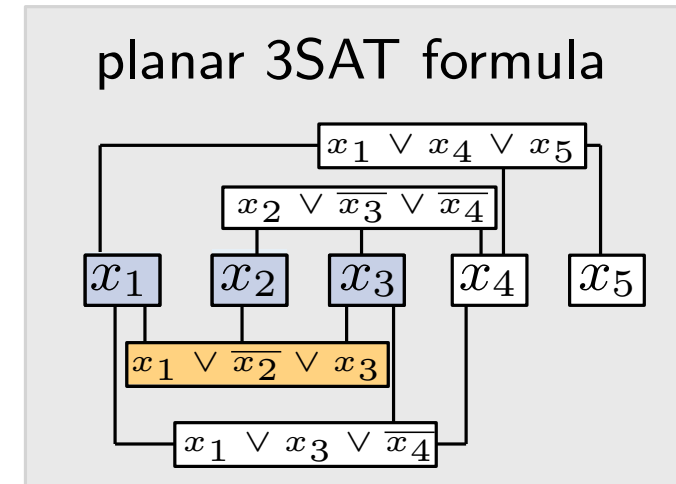
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states



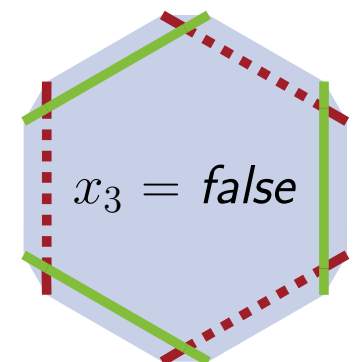
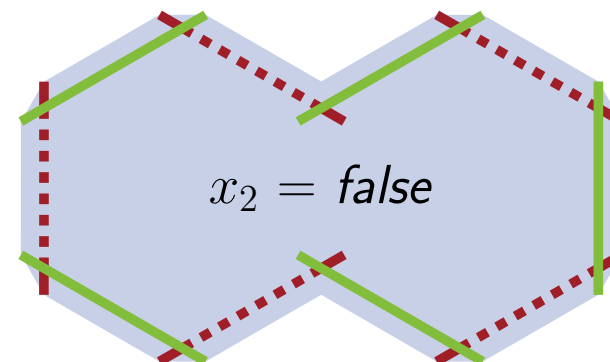
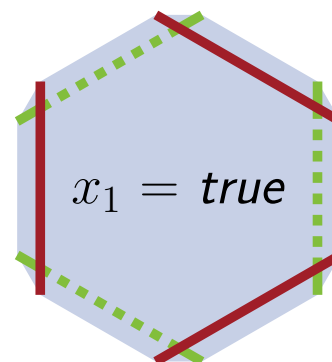
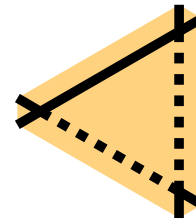
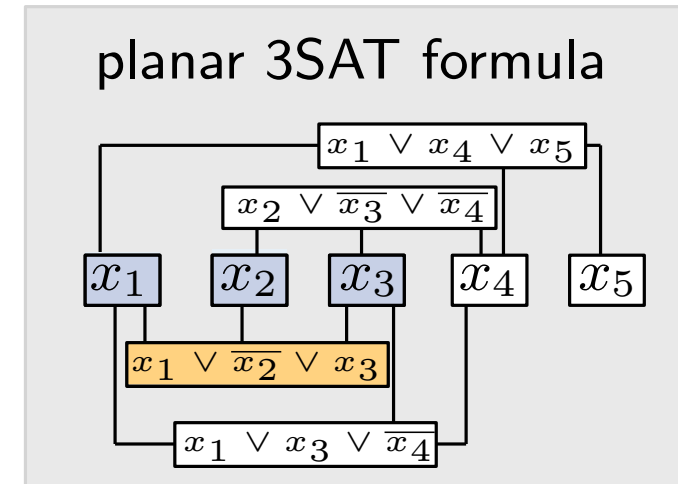
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states



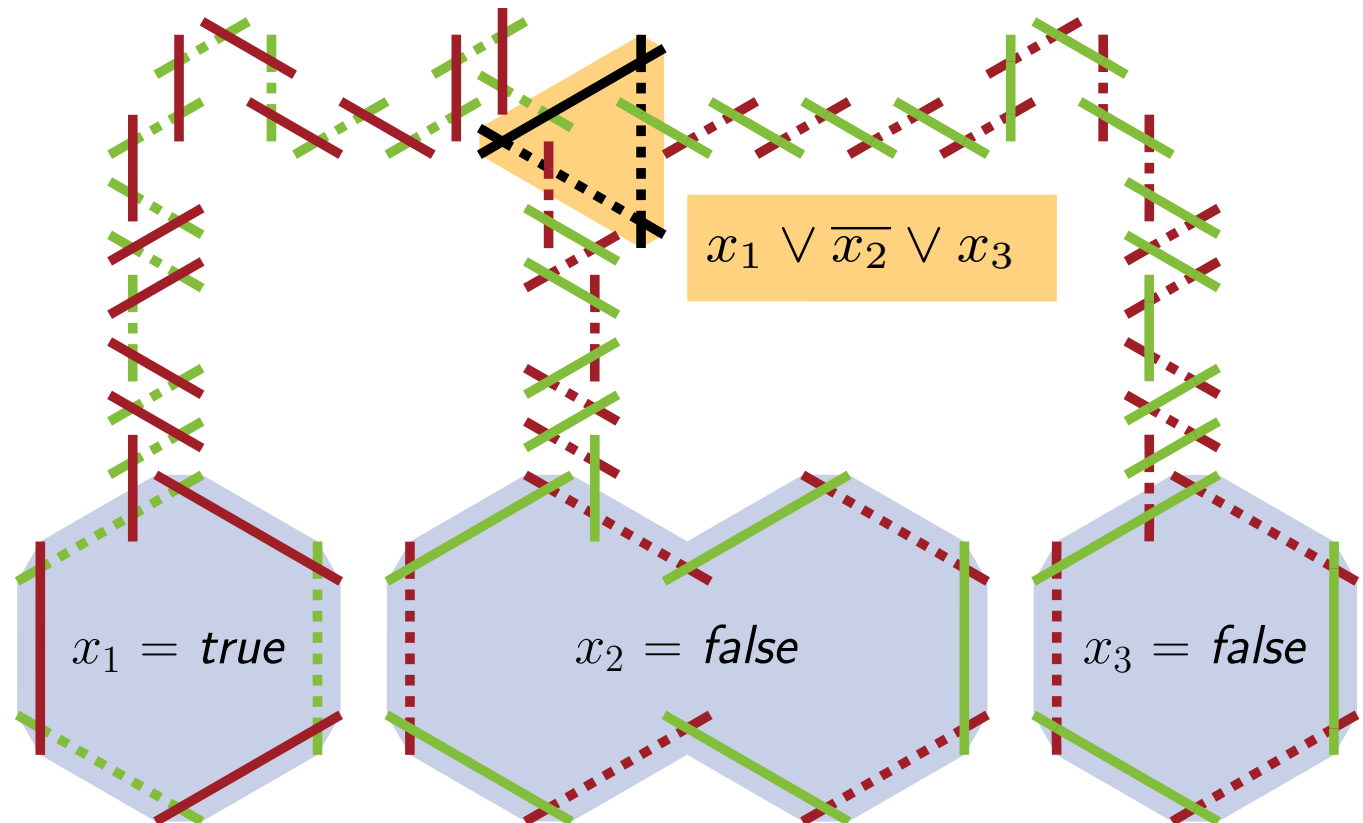
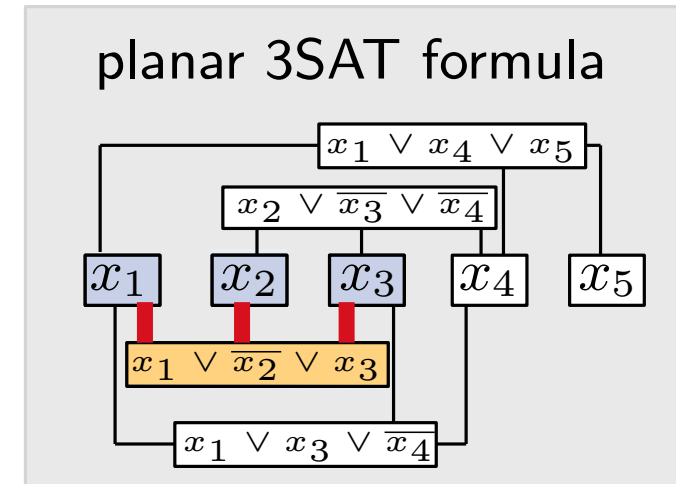
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states



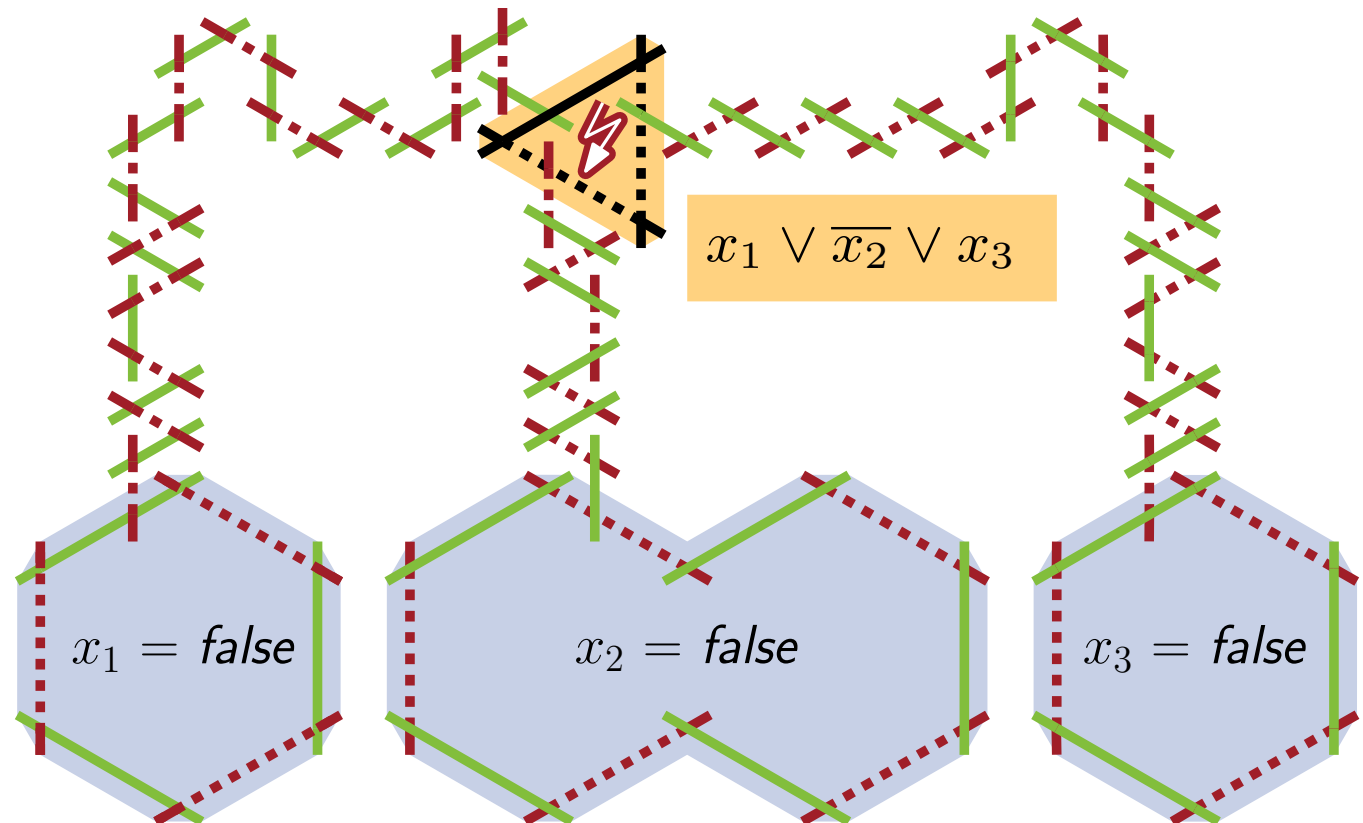
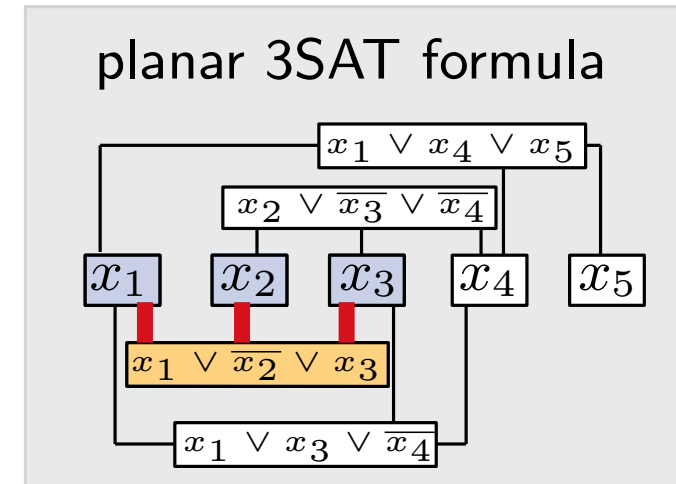
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states



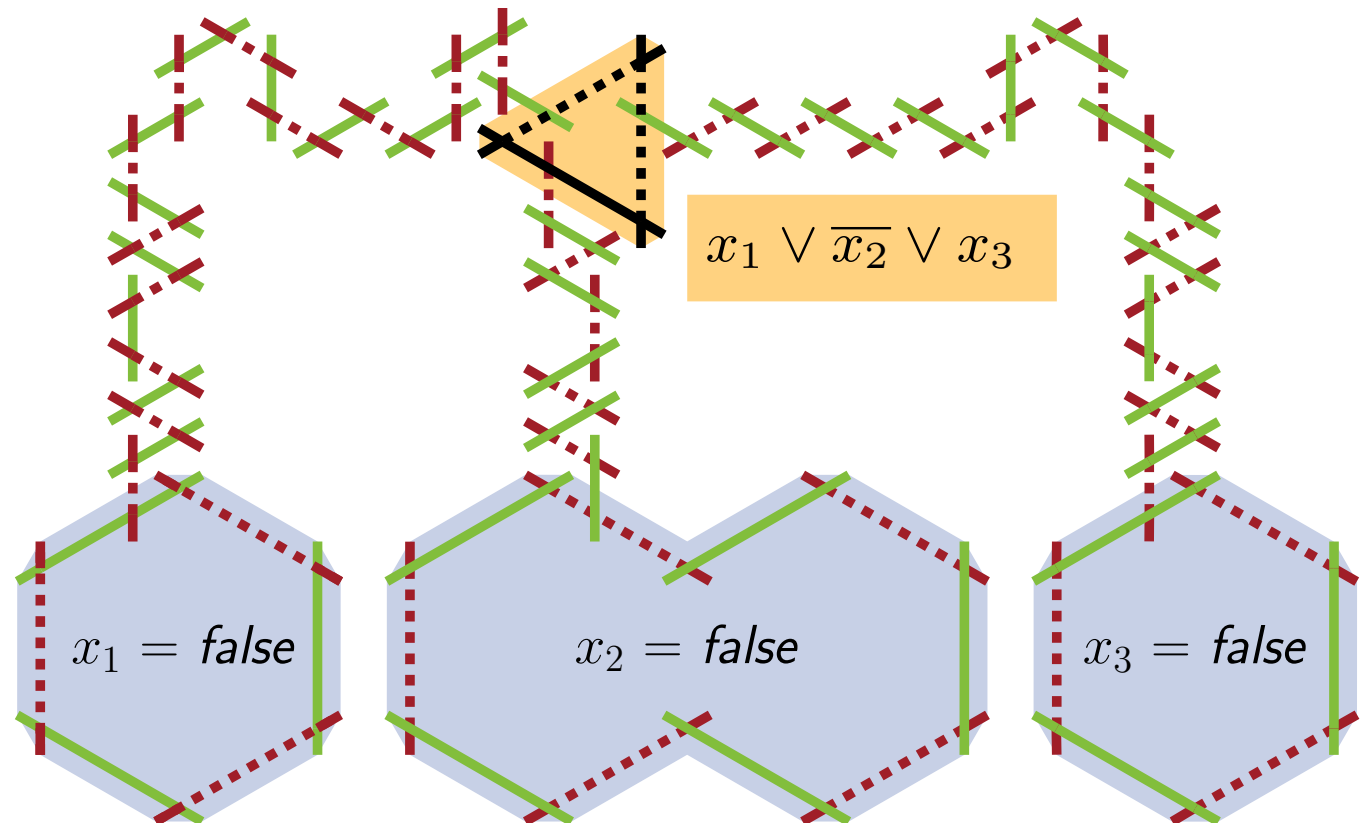
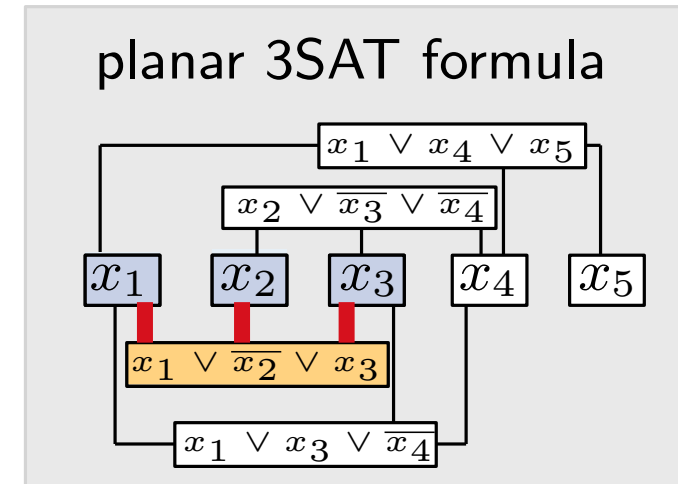
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states



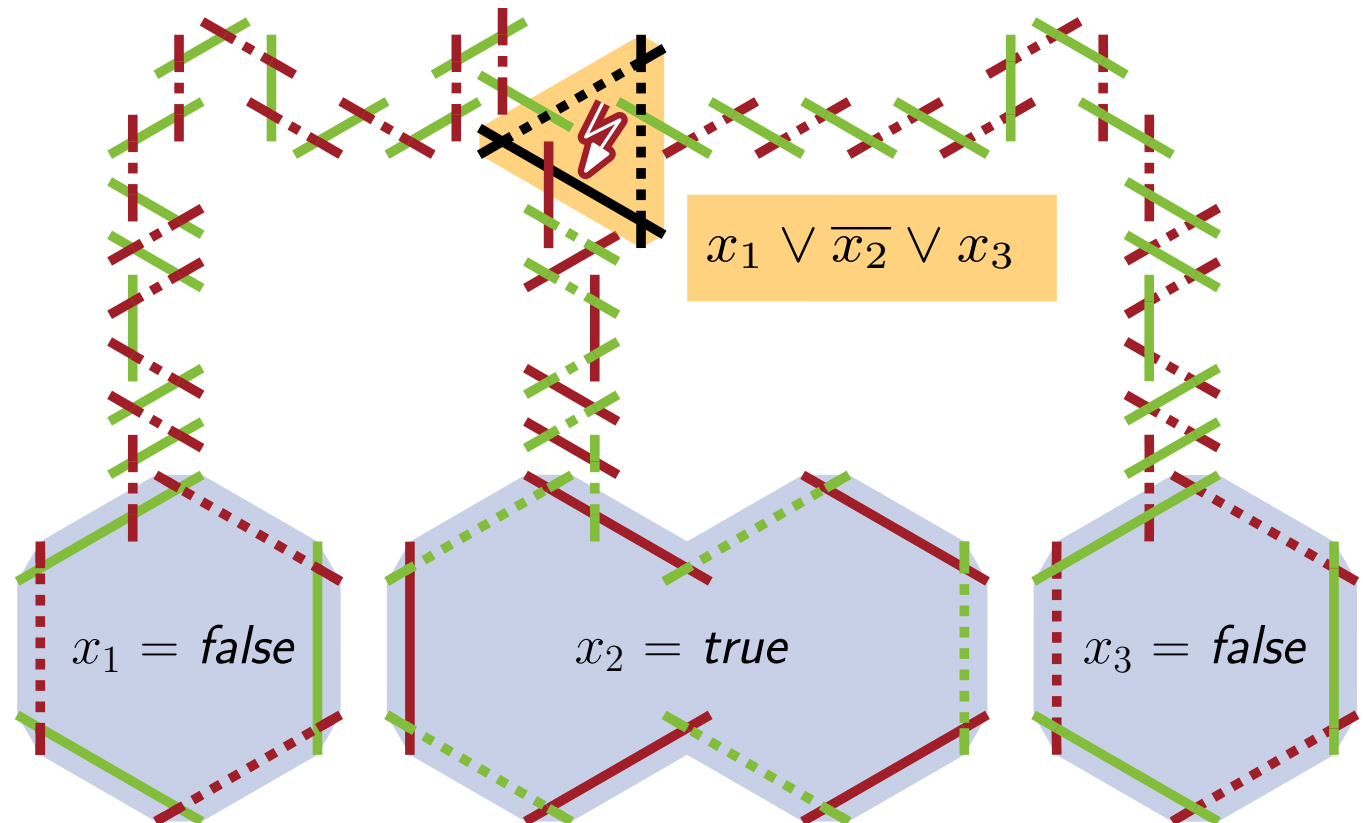
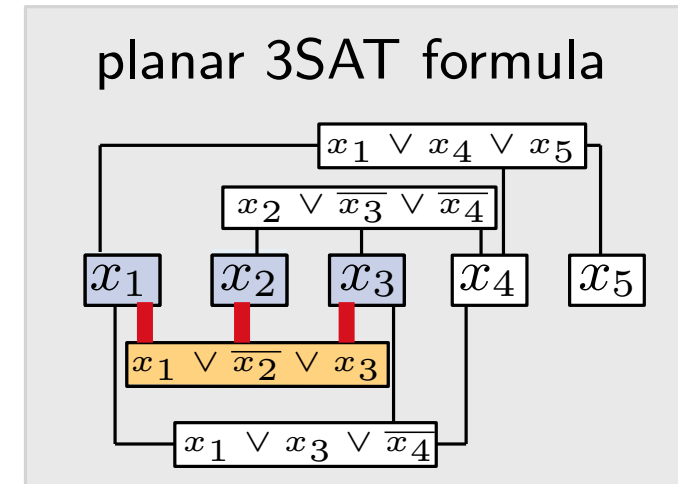
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states



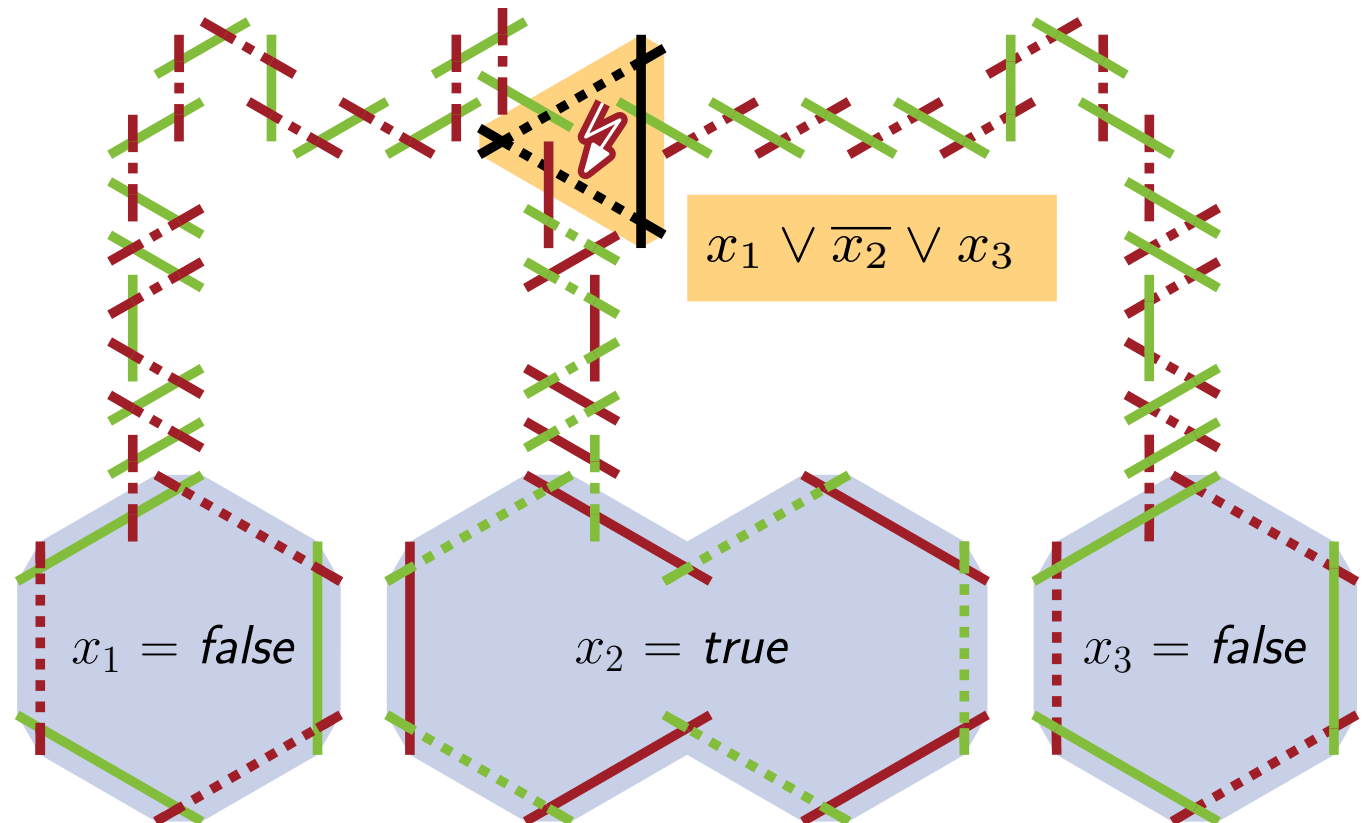
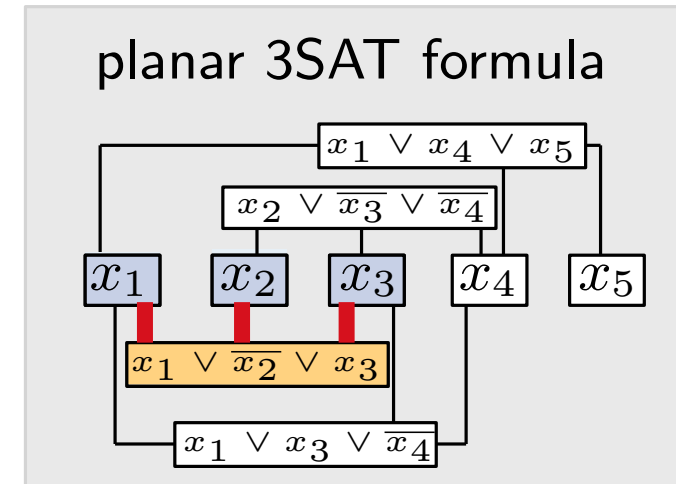
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states



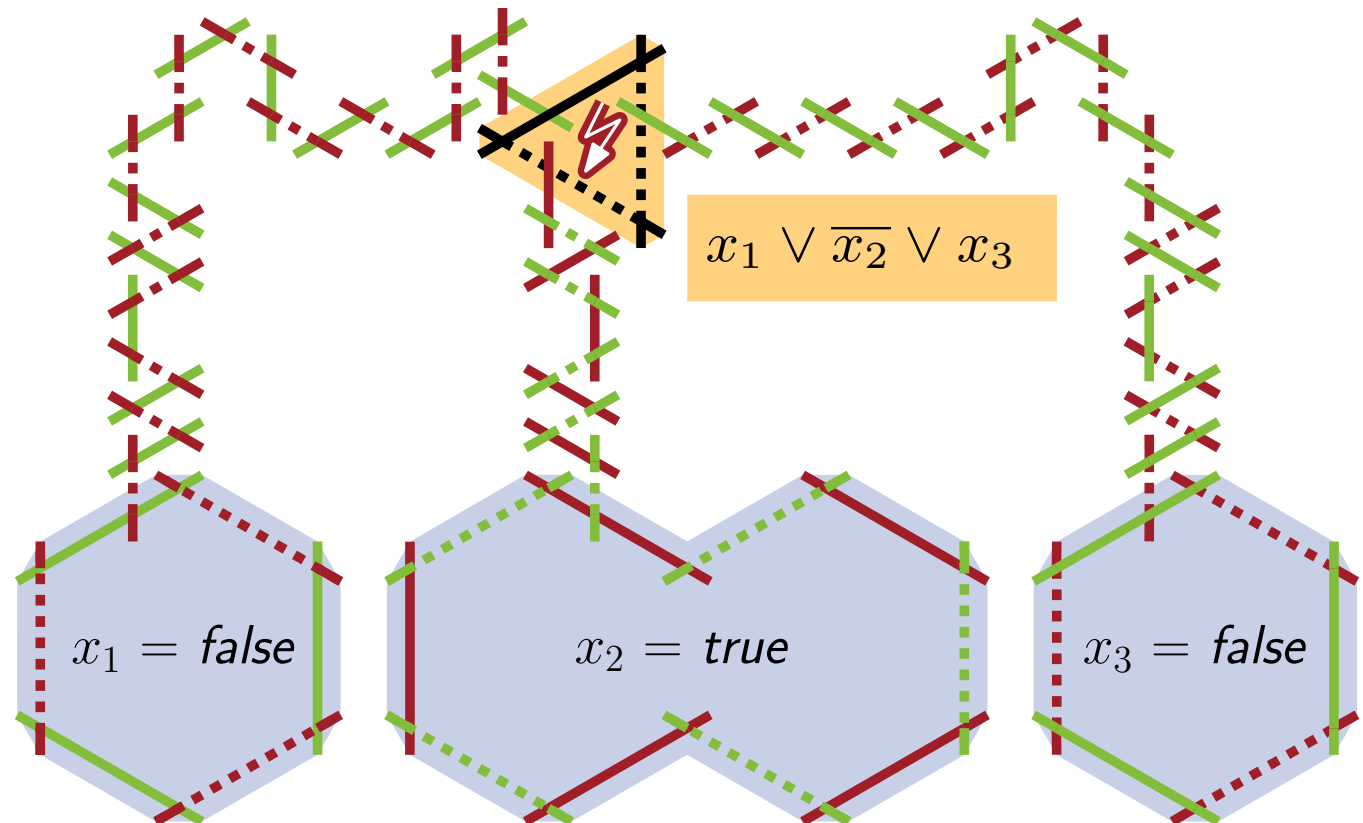
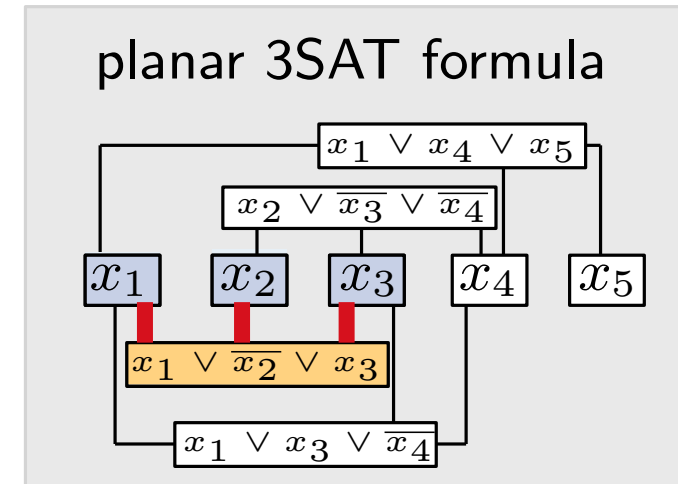
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states



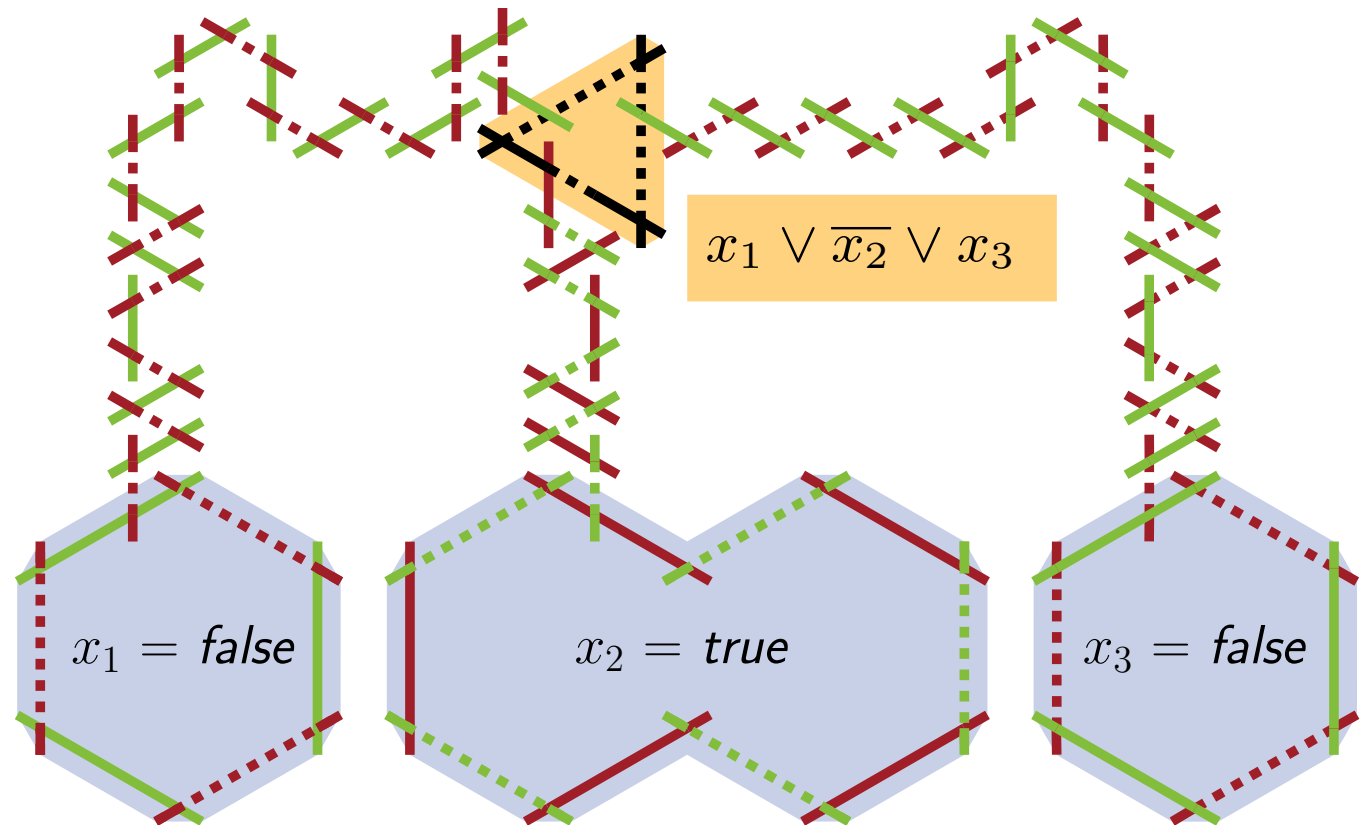
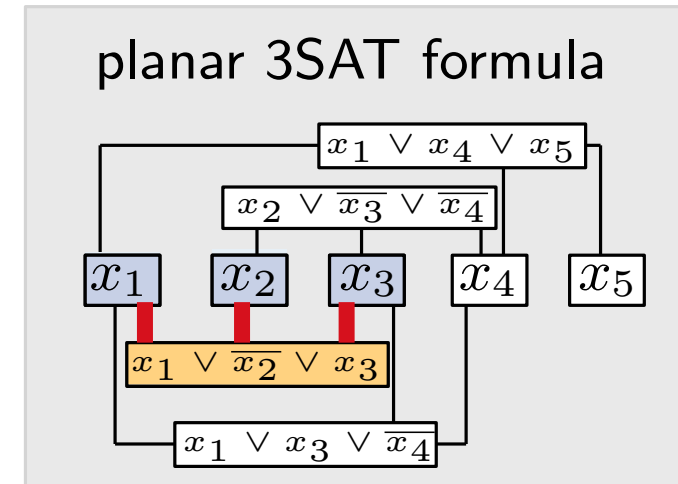
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states



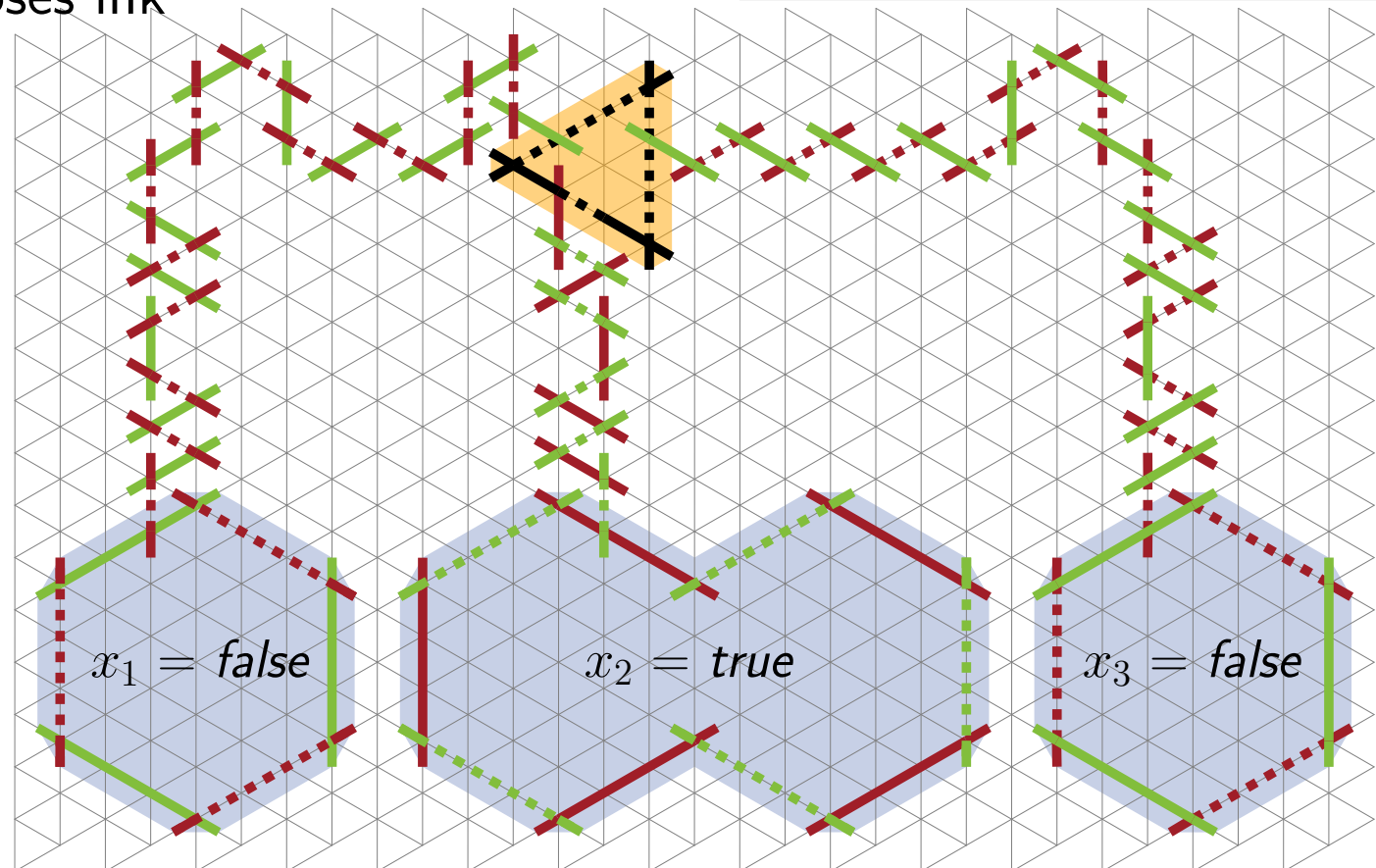
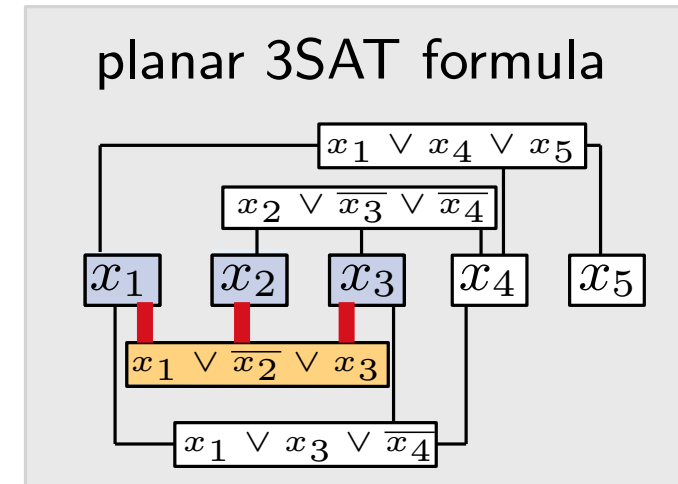
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states
 - unsatisfied clause loses ink



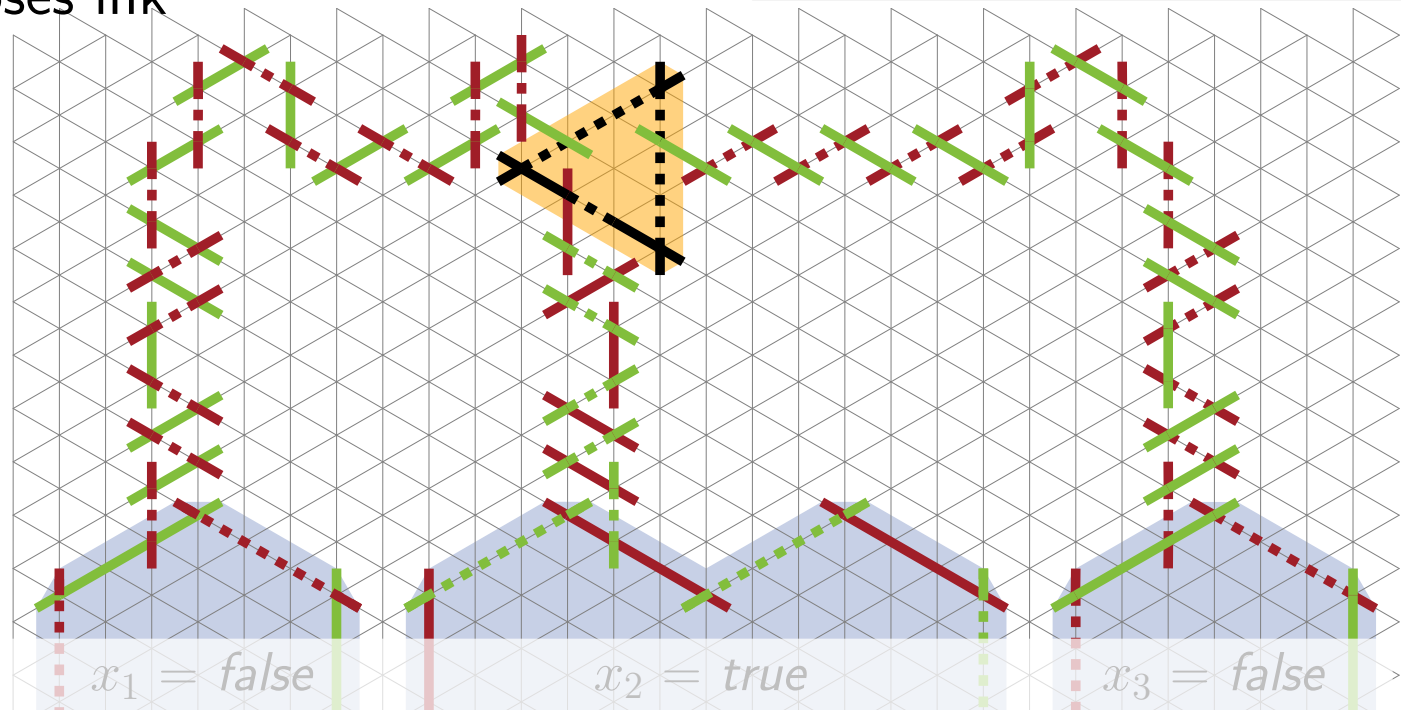
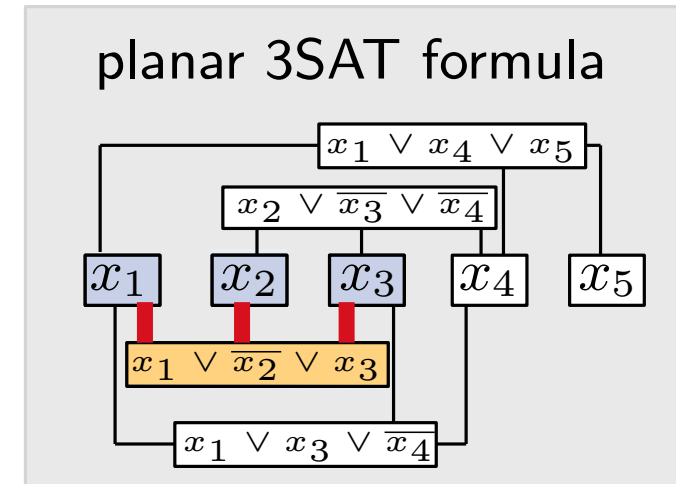
NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states
 - unsatisfied clause loses ink
 - grid placement



NP-Hardness of MaxSPED

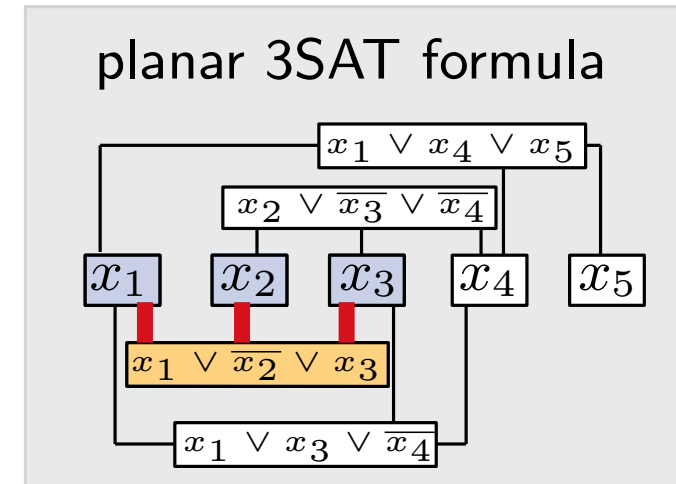
- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states
 - unsatisfied clause loses ink
 - grid placement



Theorem: MaxSPED is NP-hard for 3-plane input drawings.

NP-Hardness of MaxSPED

- reduction from PLANAR 3SAT
- gadget-based reduction
 - variable gadgets: 2 optimal states
 - clause gadgets: 3 optimal states
 - literal wires: even length paths, 2 opt. states
 - unsatisfied clause loses ink
 - grid placement



MaxPED: similar proof idea, but non-symmetric stubs require more complex gadgets and up to 4 crossings per edge.

Theorem: MaxPED is NP-hard for 4-plane input drawings.

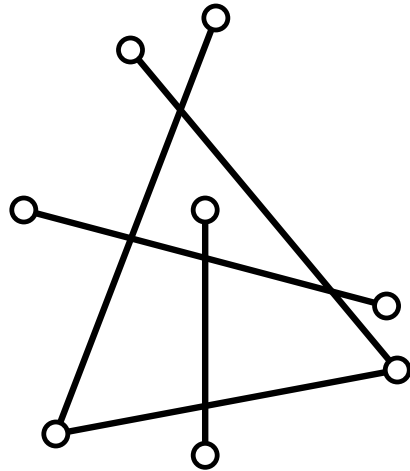
Theorem: MaxSPED is NP-hard for 3-plane input drawings.

Algorithms

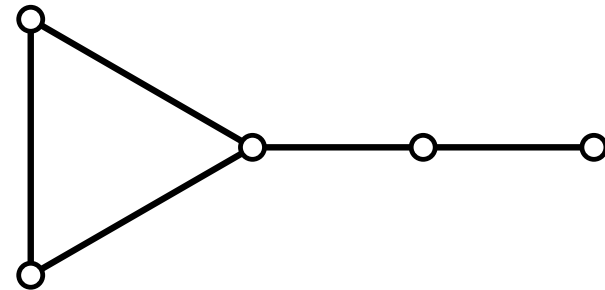
Edge Intersection Graph

- intersection graph $C(\Gamma)$: every vertex u corresponds to one segment $s(u)$ in Γ
- edge (u, v) in C iff $s(u)$ and $s(v)$ cross in Γ

drawing Γ of $G = (V, E)$



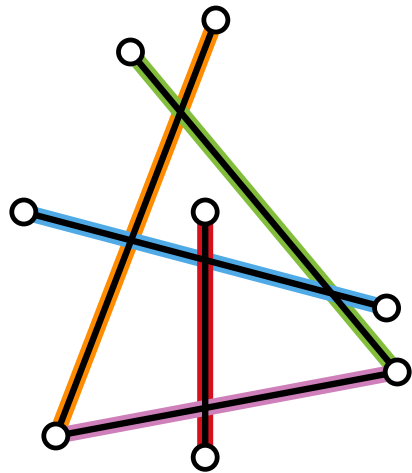
edge intersection graph
 $C(\Gamma)$ with vertex set E



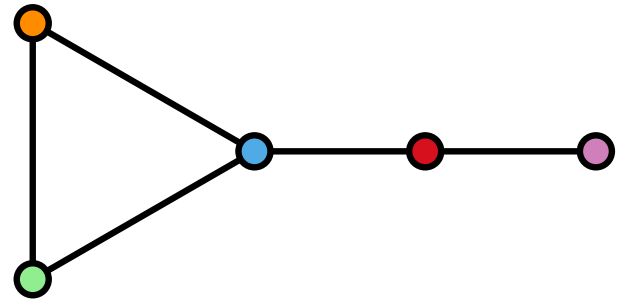
Edge Intersection Graph

- intersection graph $C(\Gamma)$: every vertex u corresponds to one segment $s(u)$ in Γ
- edge (u, v) in C iff $s(u)$ and $s(v)$ cross in Γ

drawing Γ of $G = (V, E)$



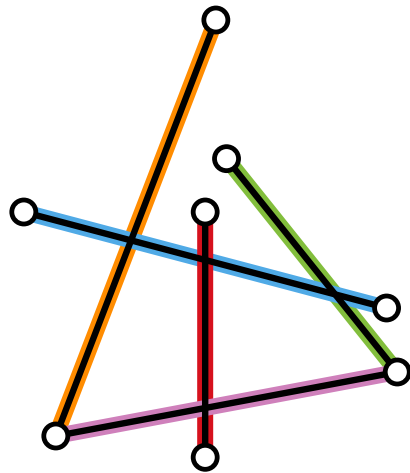
edge intersection graph
 $C(\Gamma)$ with vertex set E



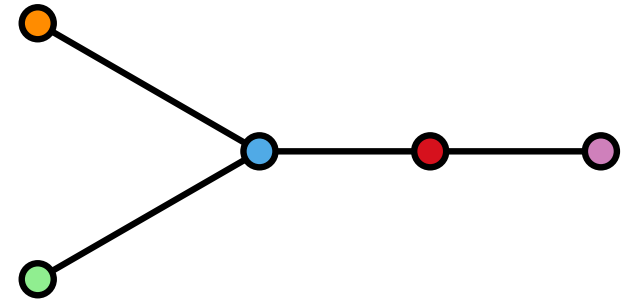
Edge Intersection Graph

- intersection graph $C(\Gamma)$: every vertex u corresponds to one segment $s(u)$ in Γ
- edge (u, v) in C iff $s(u)$ and $s(v)$ cross in Γ

drawing Γ of $G = (V, E)$



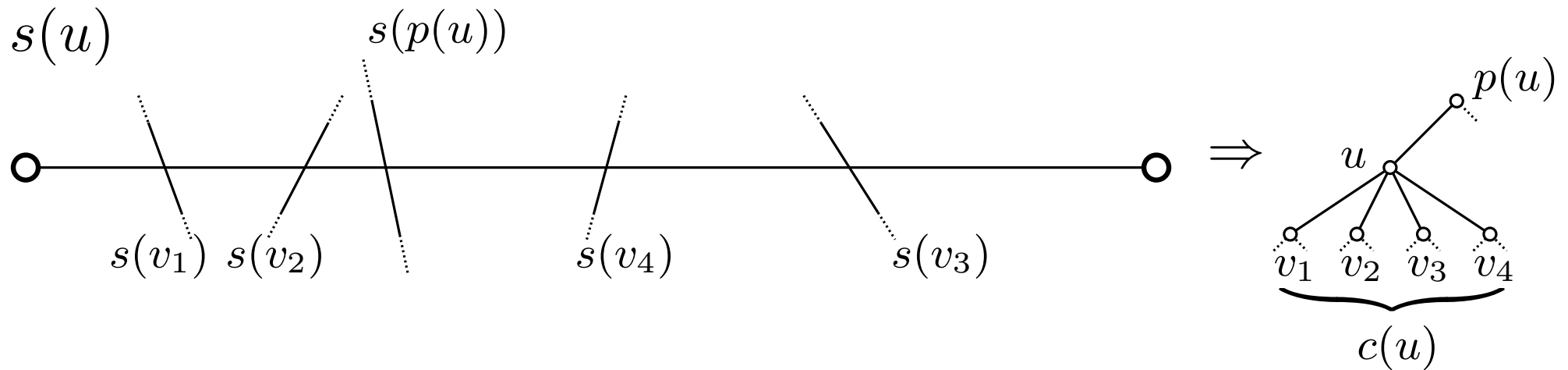
edge intersection graph
 $C(\Gamma)$ with vertex set E



First assumption: C is a tree

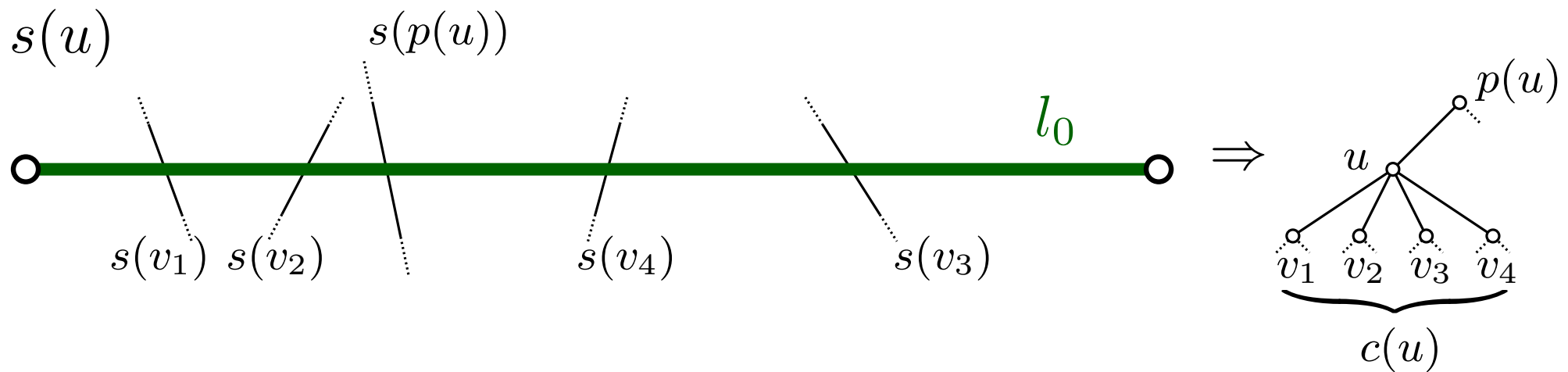
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$



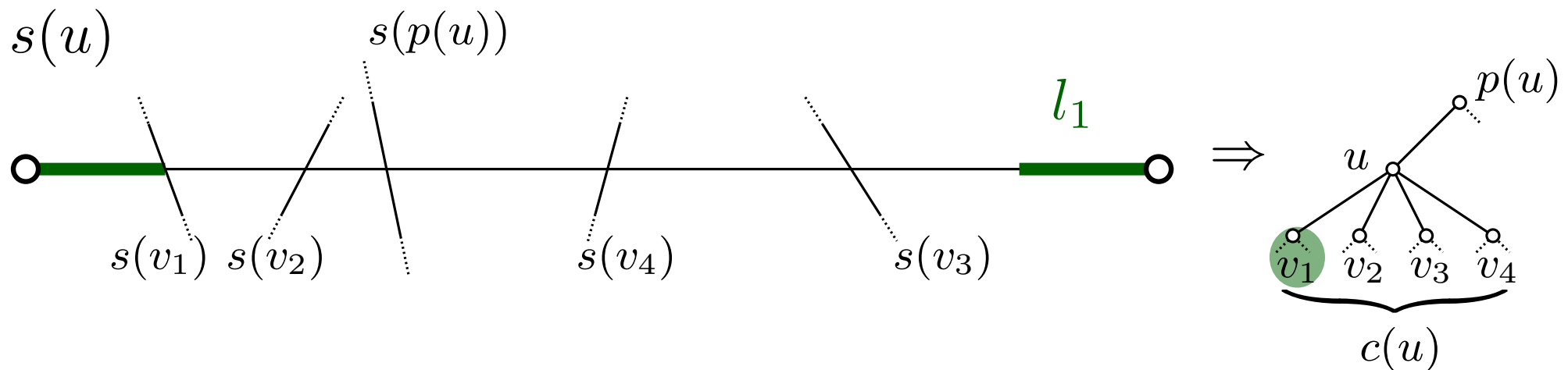
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)



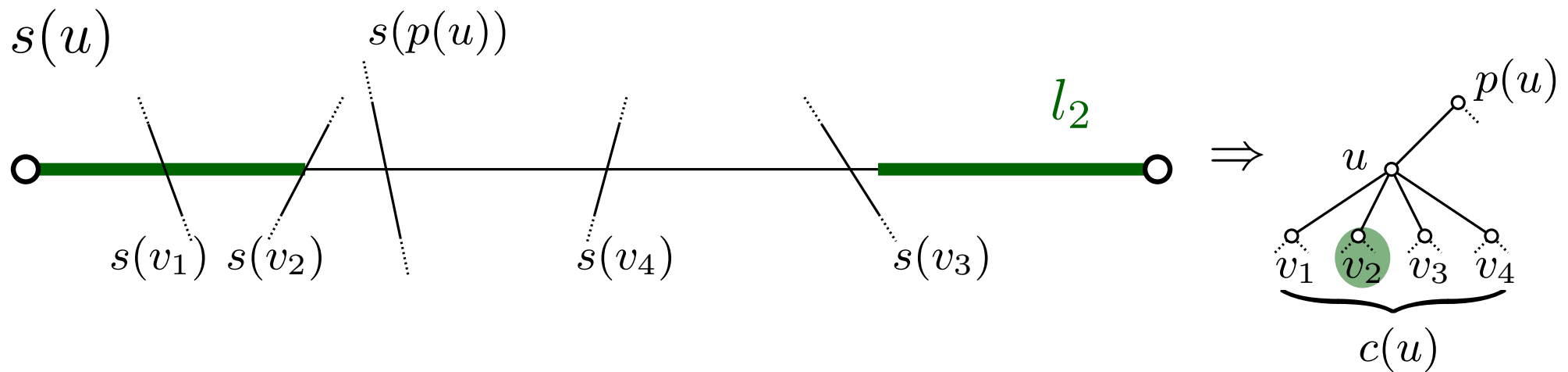
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



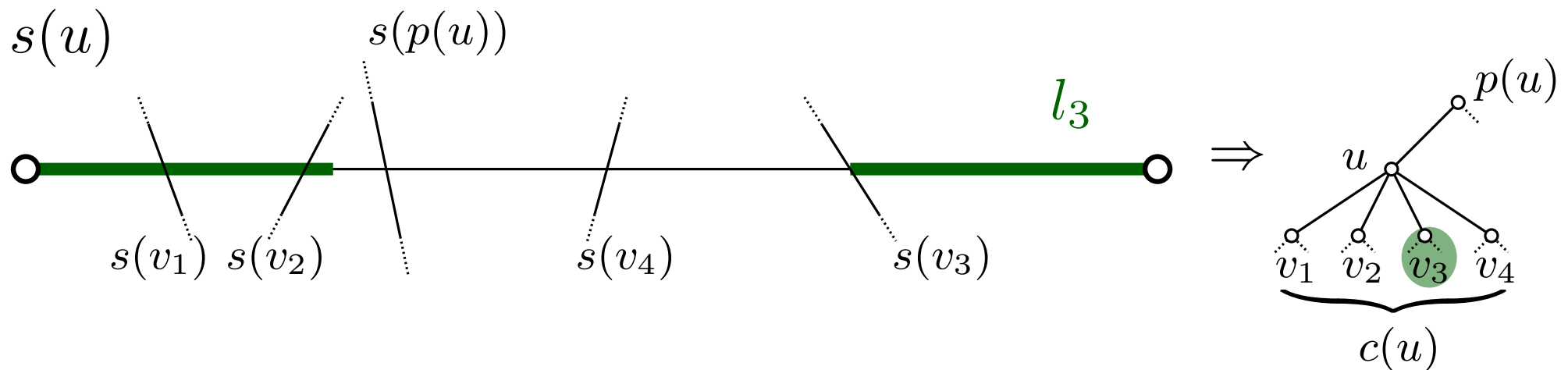
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



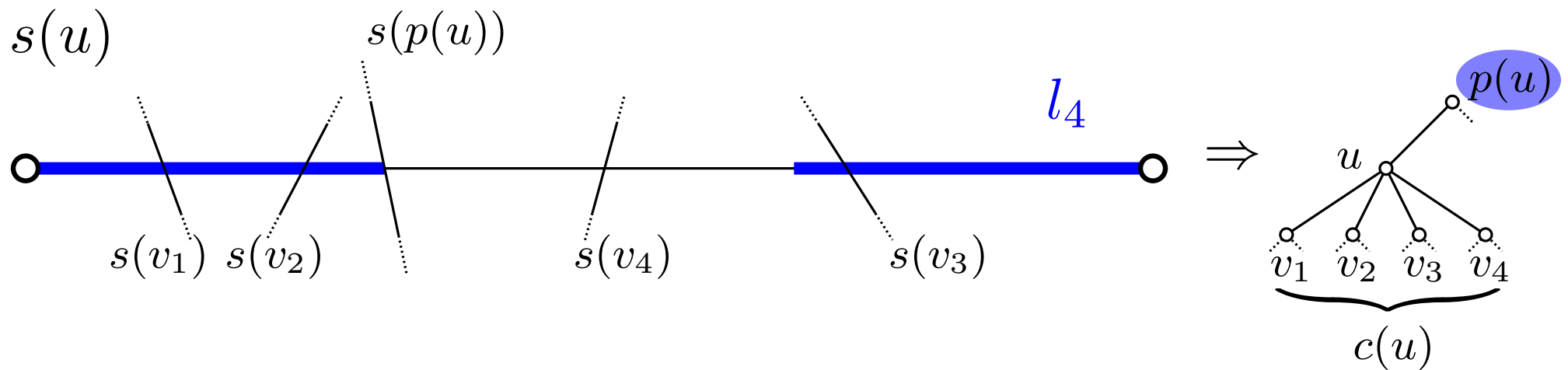
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



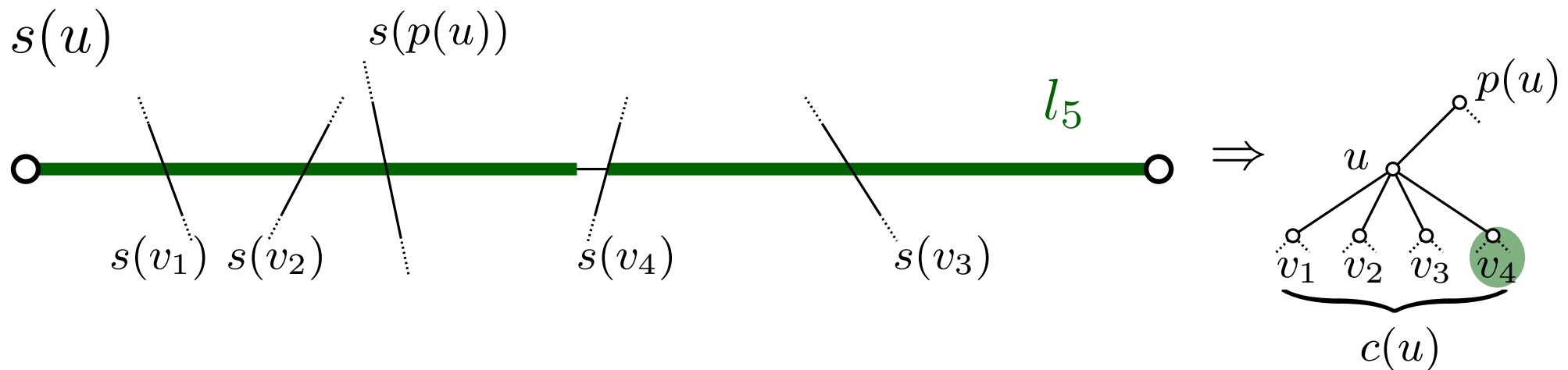
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



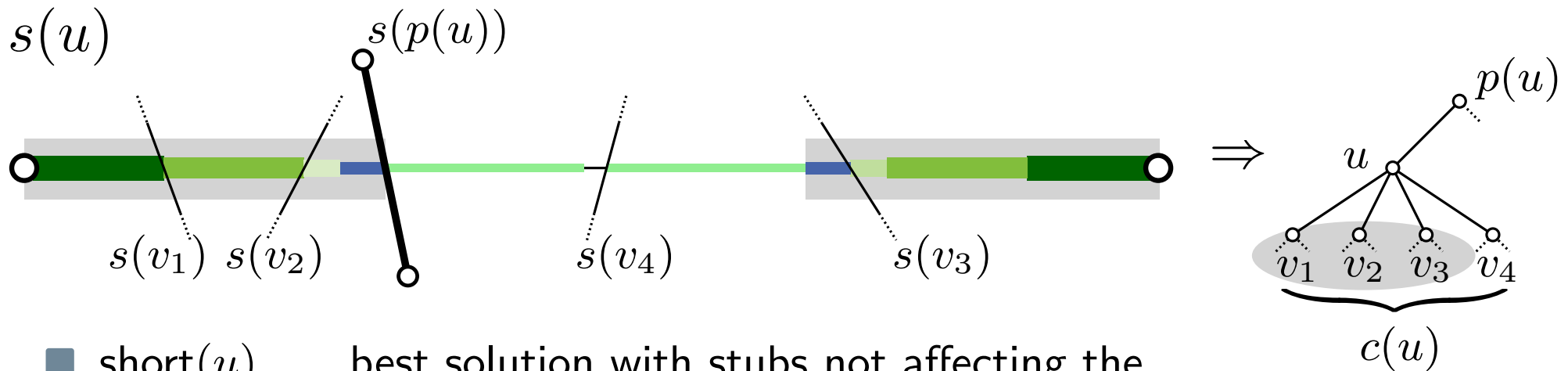
Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



Discretized Stub Lengths for MaxSPED

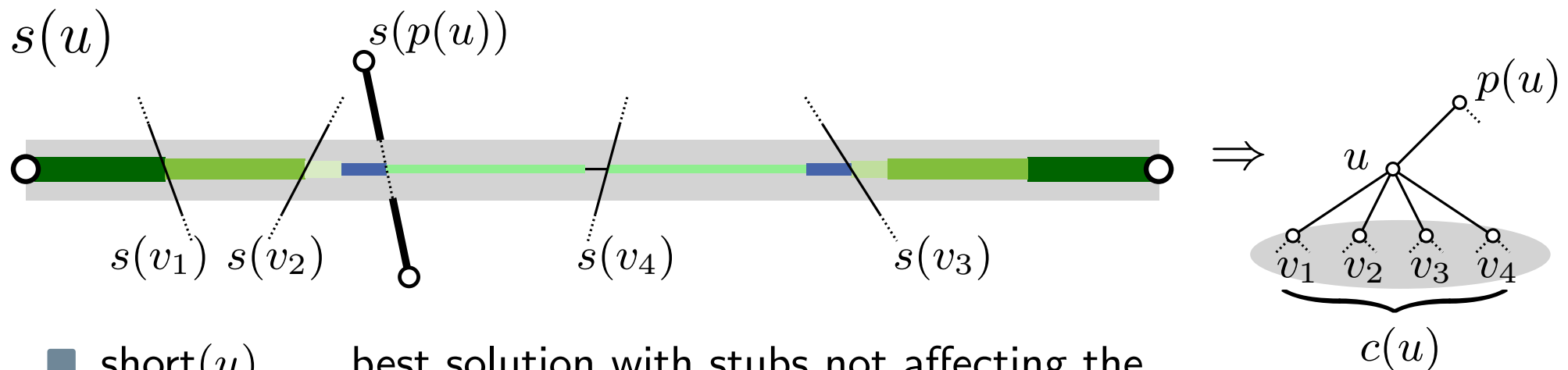
- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



- $\text{short}(u) \dots$ best solution with stubs not affecting the stubs of the parent

Discretized Stub Lengths for MaxSPED

- pick arbitrary root for tree $C(\Gamma)$
- edge crossings induce different relevant stub lengths
 - l_0 – entire edge (no gap)
 - $l_1, \dots, l_{\deg(u)}$ – shorter to longer stubs



- $\text{short}(u)$... best solution with stubs not affecting the stubs of the parent
- $\text{long}(u)$... best solution with stubs possibly affecting the stubs of the parent

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise.} \end{cases}$$

$T_i(u)$... maximum ink value for subtree rooted at u s.t. $s(u)$ has stubs of length $l_i(u)$

$s(u)$... segment for vertex u

$l_i(u)$... i -th stub length of $s(u)$

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise.} \end{cases}$$

$T_i(u)$... maximum ink value for subtree rooted at u s.t. $s(u)$ has stubs of length $l_i(u)$

$s(u)$... segment for vertex u

$l_i(u)$... i -th stub length of $s(u)$

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise.} \end{cases}$$

$c(u)$... set of children of u

$\text{short}(v) = \max\{T_1(v), \dots, T_p(v)\}$
... stubs not affecting the parent

$\text{long}(v) = \max\{T_0(v), \dots, T_{\text{deg}(v)}(v)\}$
... all stubs (possibly affecting the parent)

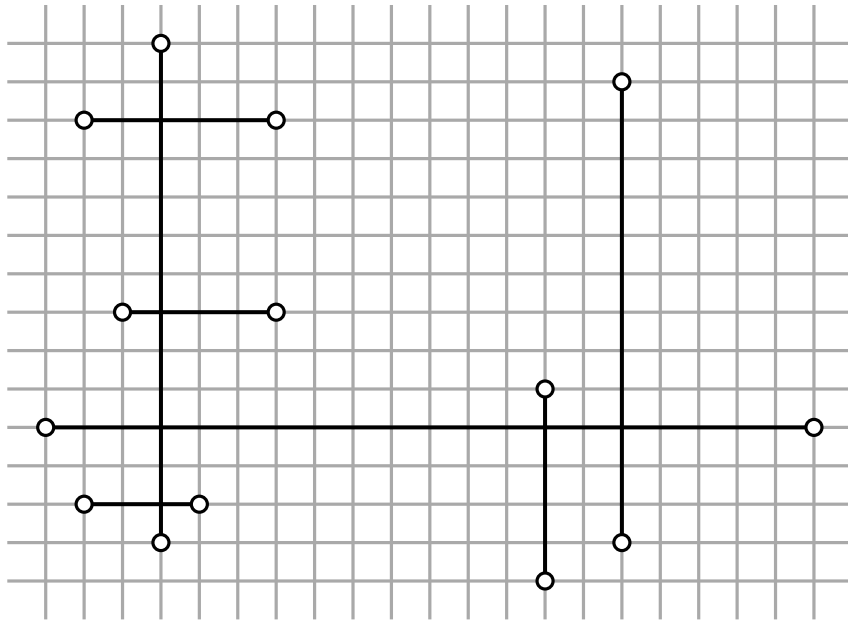
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



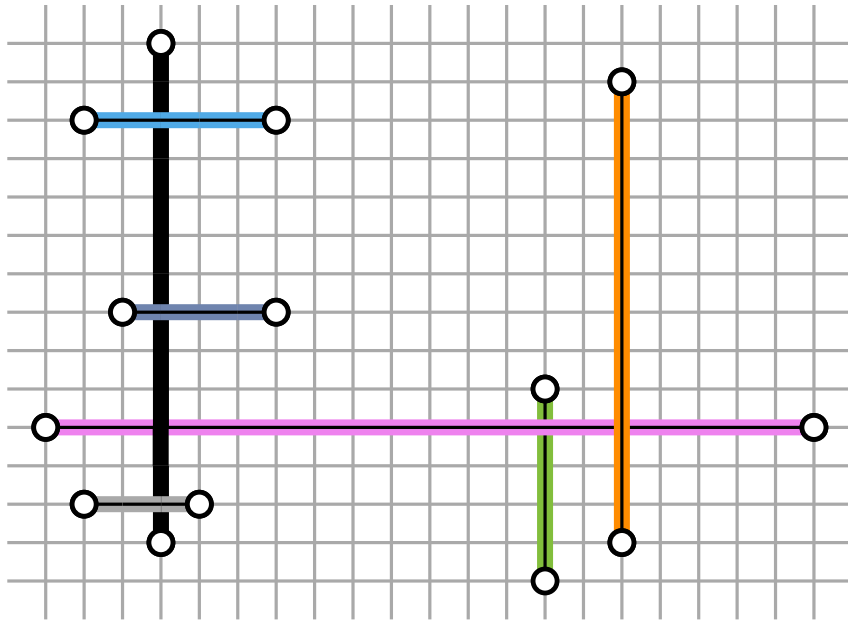
Intersection Graph:



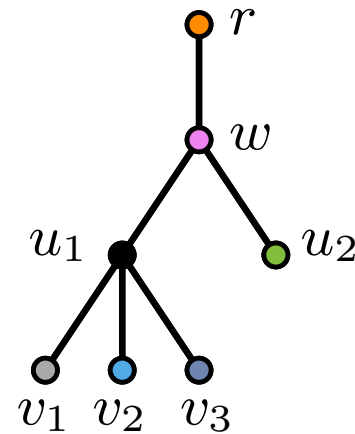
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



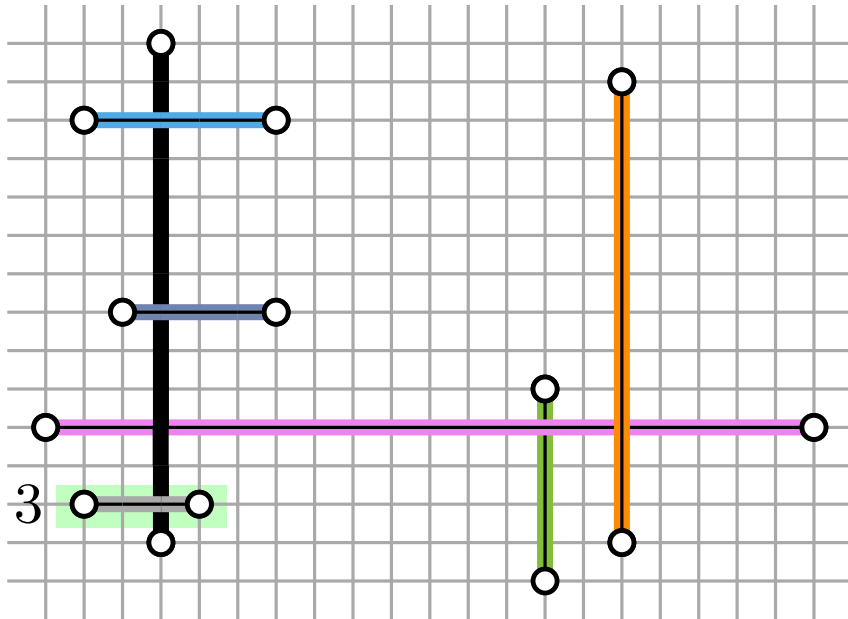
Intersection Graph:



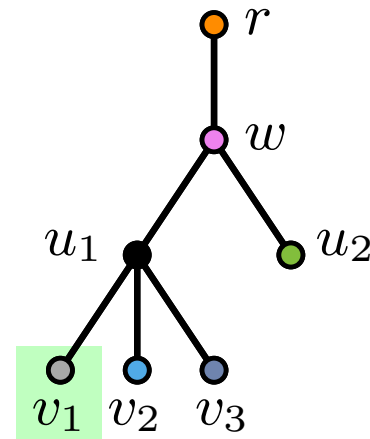
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:

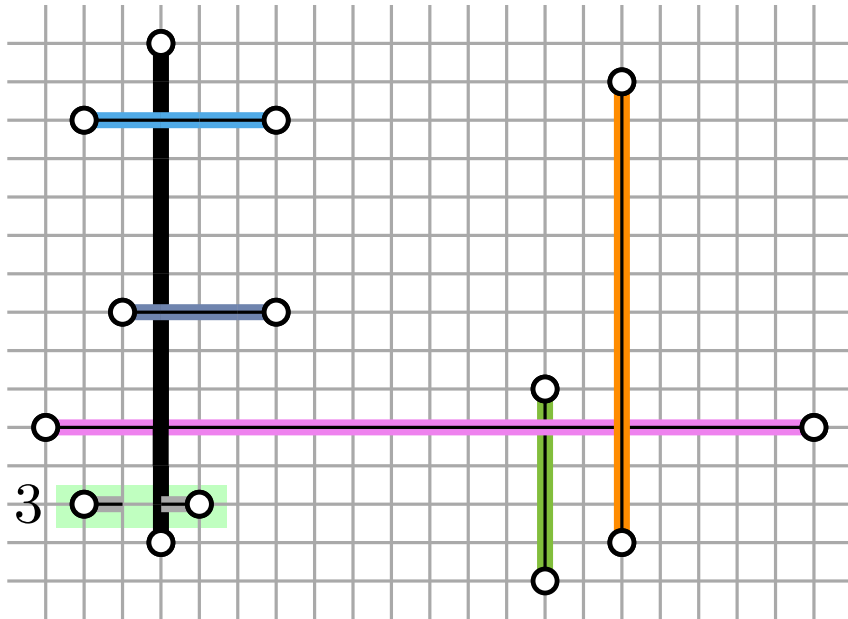


$$v_1 : T_0(v_1) = l_0 = 3$$

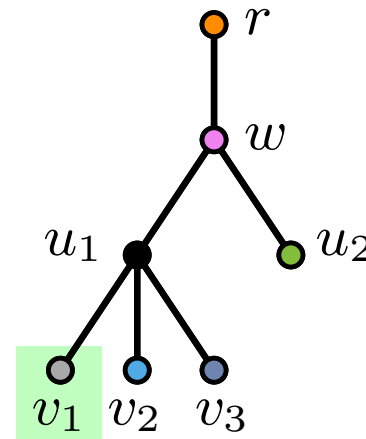
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:

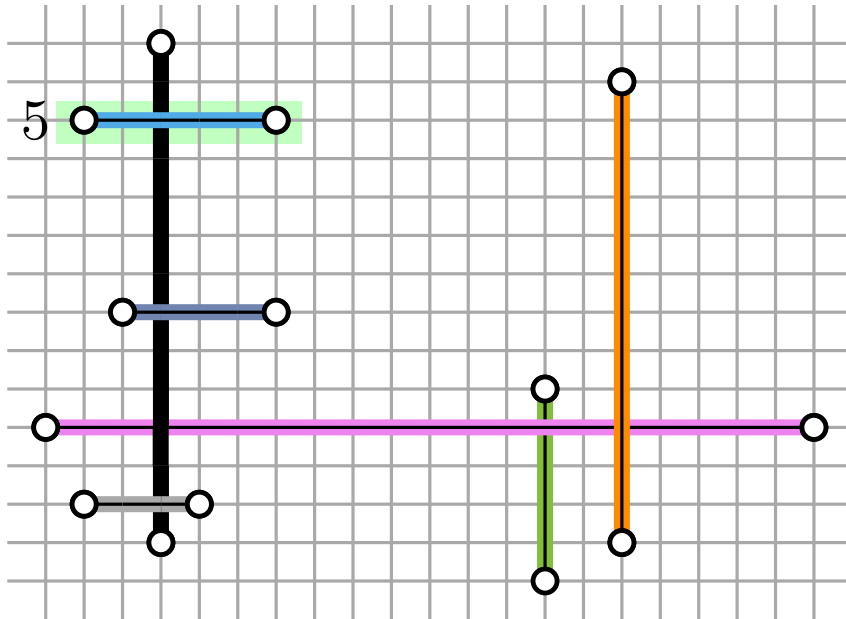


$$v_1 : \begin{array}{l} T_0(v_1) = l_0 = 3 \\ T_1(v_1) = l_1 = 2 \end{array}$$

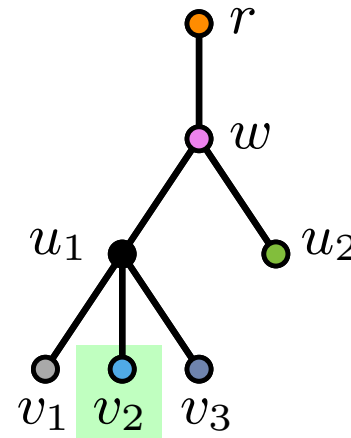
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



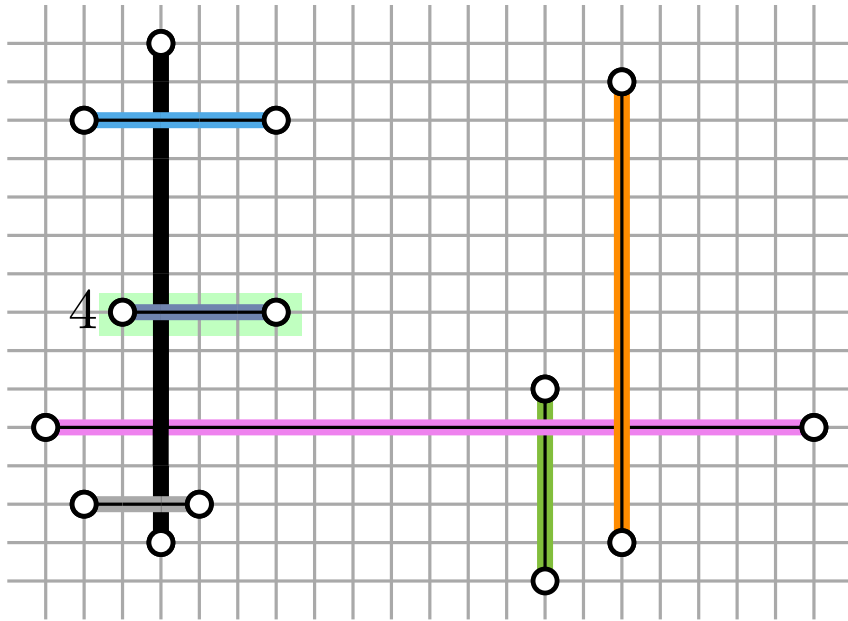
$$v_1 : \begin{array}{l} T_0(v_1) = 3 \\ T_1(v_1) = 2 \end{array}$$

$$v_2 : \begin{array}{l} T_0(v_2) = l_0 = 5 \\ T_1(v_2) = l_1 = 4 \end{array}$$

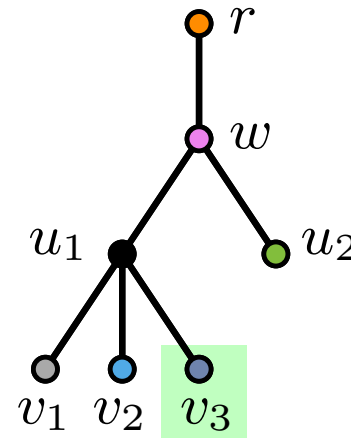
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



$v_1 :$	$T_0(v_1)$	$= 3$
	$T_1(v_1)$	$= 2$

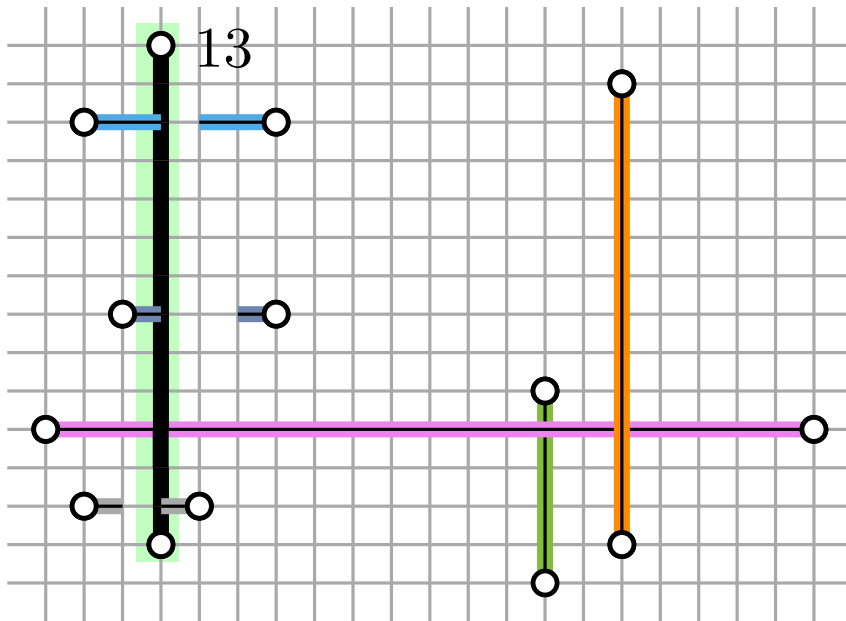
$v_2 :$	$T_0(v_2)$	$= 5$
	$T_1(v_2)$	$= 4$

$v_3 :$	$T_0(v_3) = l_0$	$= 4$
	$T_1(v_3) = l_1$	$= 2$

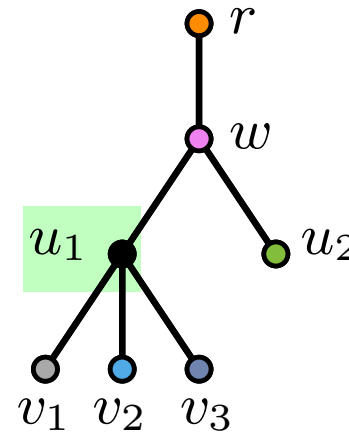
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



v_1 :	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2 :	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3 :	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

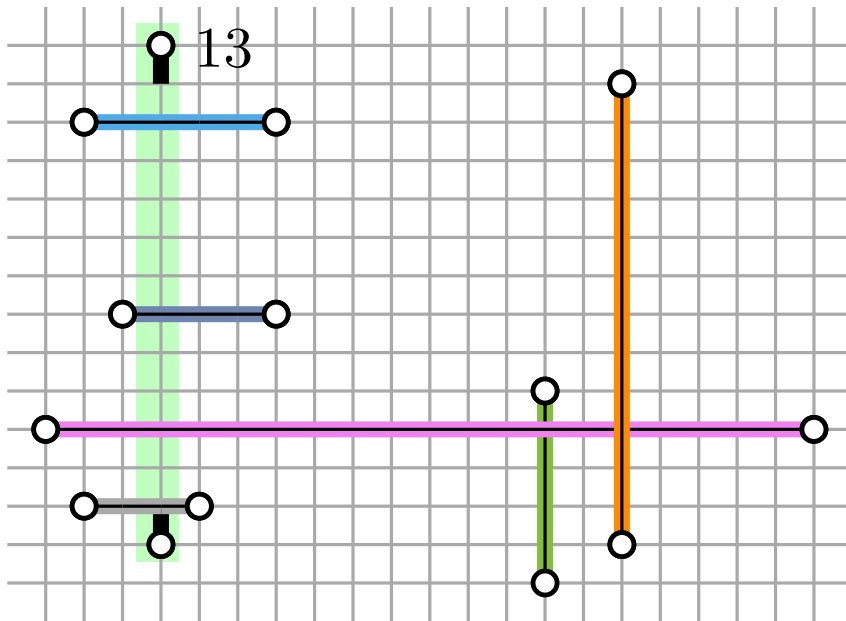
$$T_0(u_1) = l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) = 21$$

u_1 :

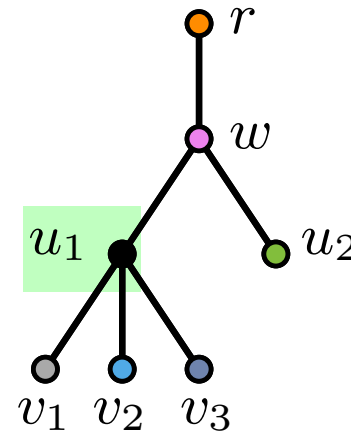
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



v_1 :	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2 :	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3 :	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

$$T_0(u_1) = l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) = 21$$

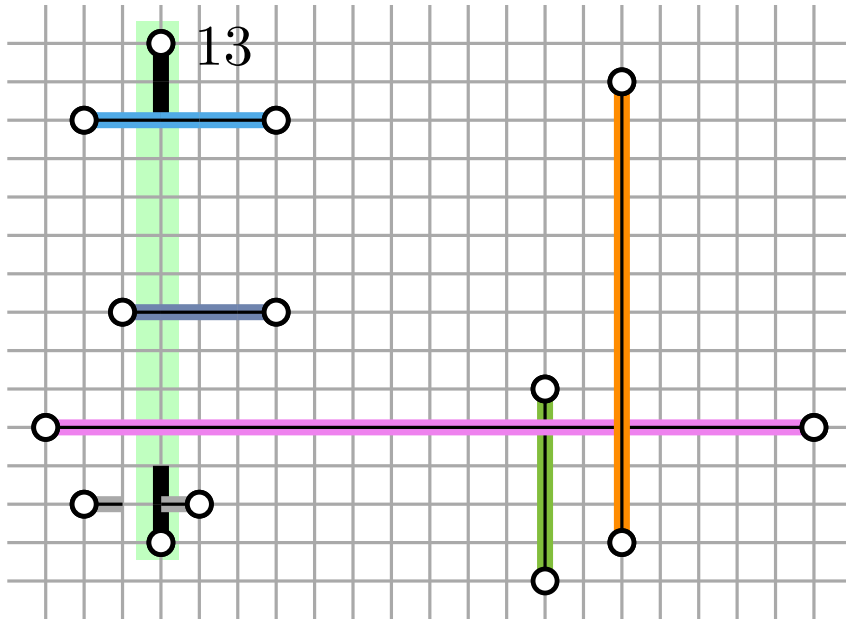
$$T_1(u_1) = l_1 + \text{long}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 14$$

u_1 :

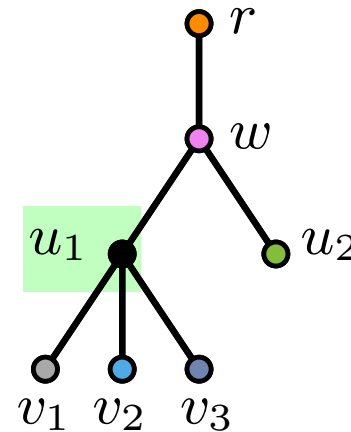
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



v_1 :	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2 :	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3 :	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

$$T_0(u_1) = l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) = 21$$

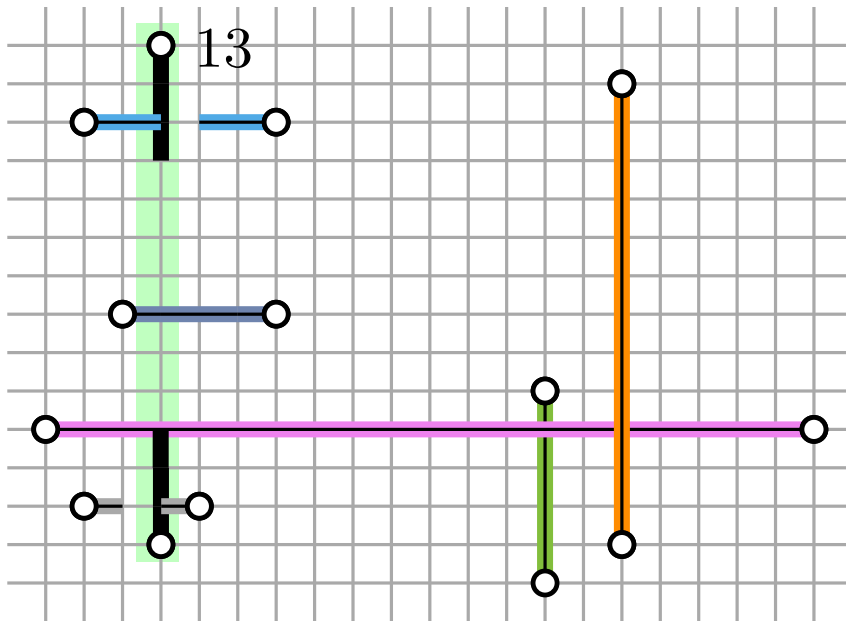
$$T_1(u_1) = l_1 + \text{long}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 14$$

$$u_1 : T_2(u_2) = l_2 + \text{short}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 15$$

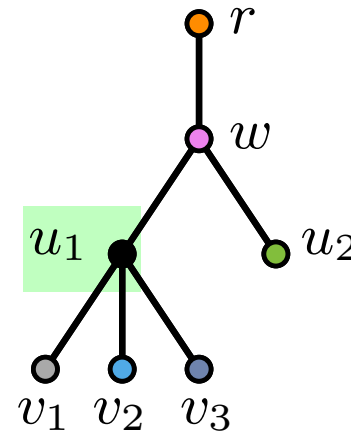
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



v_1 :	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2 :	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3 :	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

$$T_0(u_1) = l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) = 21$$

$$T_1(u_1) = l_1 + \text{long}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 14$$

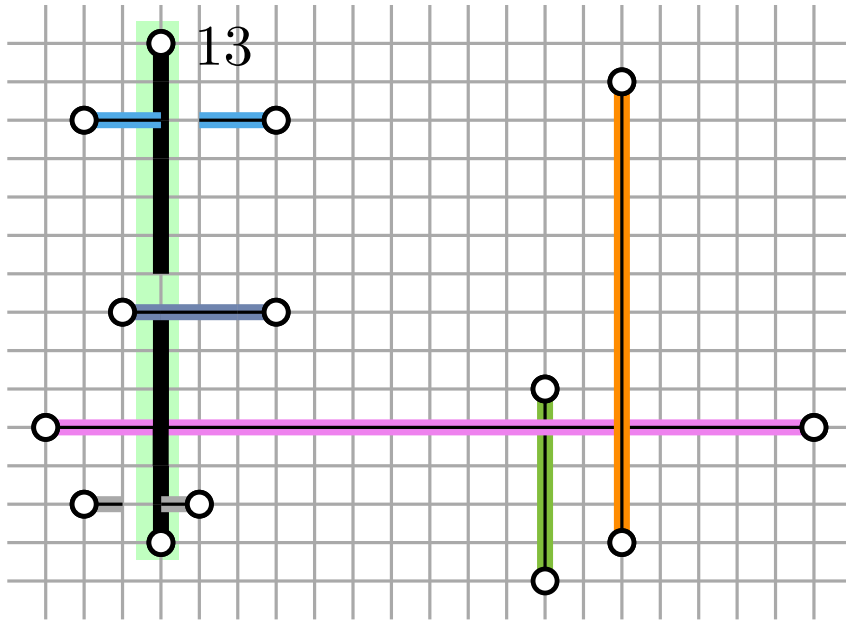
$$u_1 : T_2(u_2) = l_2 + \text{short}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 15$$

$$T_3(u_3) = l_3 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) = 16$$

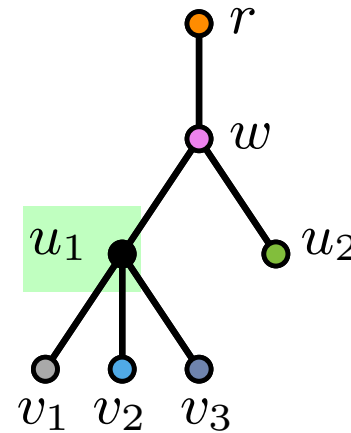
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



v_1 :	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2 :	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3 :	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

$$T_0(u_1) = l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) = 21$$

$$T_1(u_1) = l_1 + \text{long}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 14$$

$$u_1 : T_2(u_2) = l_2 + \text{short}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 15$$

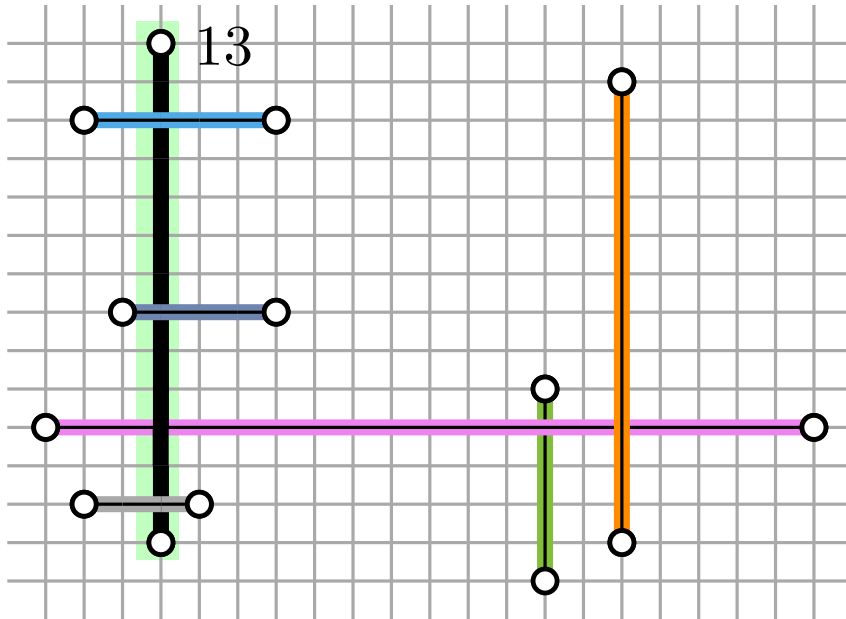
$$T_3(u_3) = l_3 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) = 16$$

$$T_4(u_4) = l_4 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) = 22$$

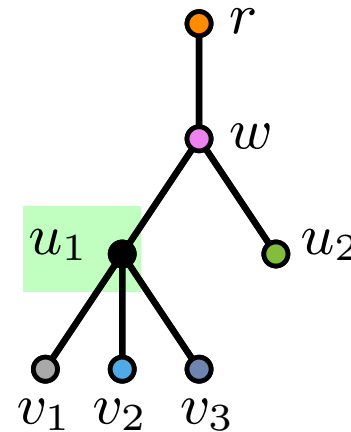
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



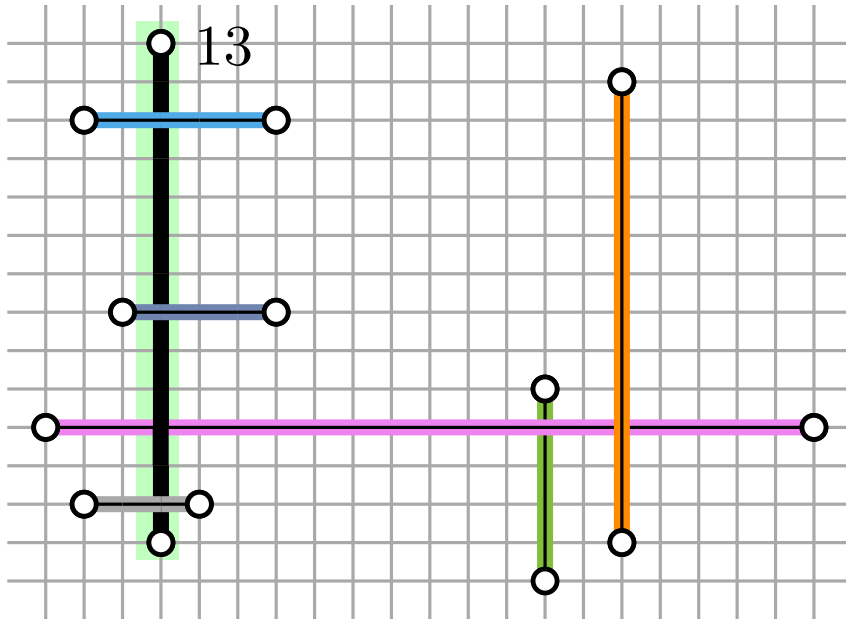
v_1 :	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2 :	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3 :	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

$$\begin{aligned}
 T_0(u_1) &= l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) &= 21 \\
 T_1(u_1) &= l_1 + \text{long}(v_1) + \text{long}(v_2) + \text{long}(v_3) &= 14 \\
 u_1 : T_2(u_2) &= l_2 + \text{short}(v_1) + \text{long}(v_2) + \text{long}(v_3) &= 15 \\
 T_3(u_3) &= l_3 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) &= 16 \\
 T_4(u_4) &= l_4 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) &= 22
 \end{aligned}
 \left. \begin{array}{l} \\ \\ \\ \\ \end{array} \right\} \begin{array}{l} \text{short}(u_1) = \\ \max\{T_1, T_2, T_3\} = \\ T_3(u_1) = 16 \end{array}$$

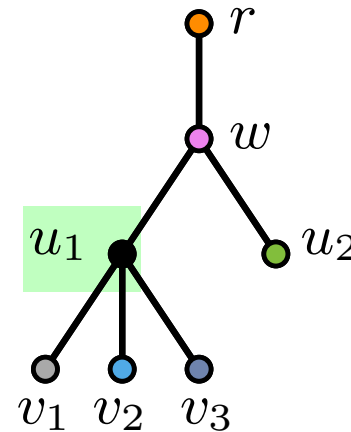
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



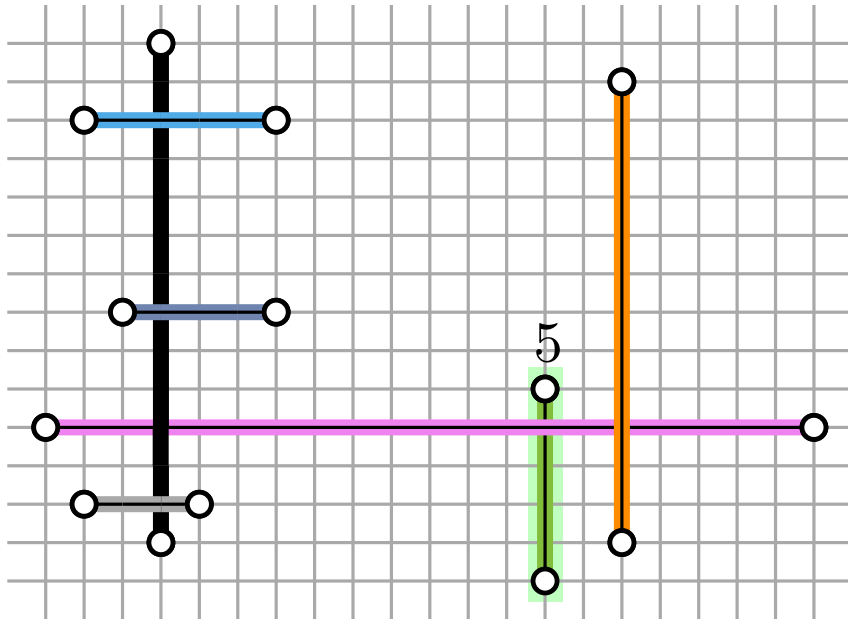
v_1	$T_0(v_1)$	= 3
	$T_1(v_1)$	= 2
v_2	$T_0(v_2)$	= 5
	$T_1(v_2)$	= 4
v_3	$T_0(v_3)$	= 4
	$T_1(v_3)$	= 2

$$\begin{array}{l}
 T_0(u_1) = l_0 + \text{short}(v_1) + \text{short}(v_2) + \text{short}(v_3) = 21 \\
 T_1(u_1) = l_1 + \text{long}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 14 \\
 u_1 : T_2(u_2) = l_2 + \text{short}(v_1) + \text{long}(v_2) + \text{long}(v_3) = 15 \\
 T_3(u_3) = l_3 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) = 16 \\
 T_4(u_4) = l_4 + \text{short}(v_1) + \text{short}(v_2) + \text{long}(v_3) = 22
 \end{array}
 \left. \vphantom{\begin{array}{l} T_0(u_1) \\ T_1(u_1) \\ T_2(u_2) \\ T_3(u_3) \\ T_4(u_4) \end{array}} \right\} \begin{array}{l} \text{long}(u_1) = \\ \max\{T_0, \dots, T_4\} = \\ T_4(u_1) = 22 \end{array}$$

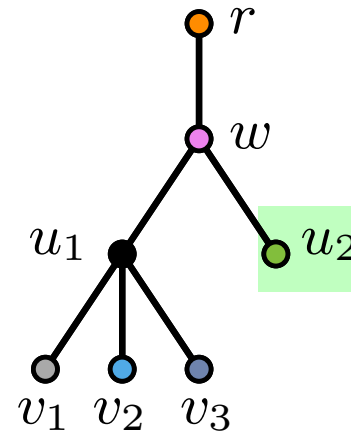
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



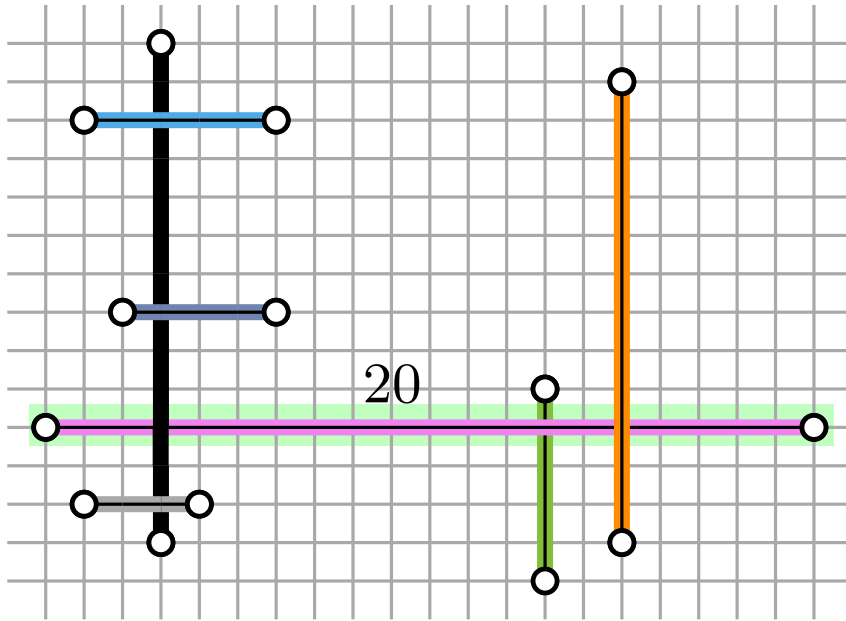
v_1 :	$T_0(v_1)$	=	3
	$T_1(v_1)$	=	2
v_2 :	$T_0(v_2)$	=	5
	$T_1(v_2)$	=	4
v_3 :	$T_0(v_3)$	=	4
	$T_1(v_3)$	=	2
u_1 :	$\text{short}(u_1) = T_3$	=	16
	$\text{long}(u_1) = T_4$	=	22

$$u_2 : \begin{cases} T_0(u_2) = l_0 & = 5 \\ T_1(u_2) = l_1 & = 2 \end{cases}$$

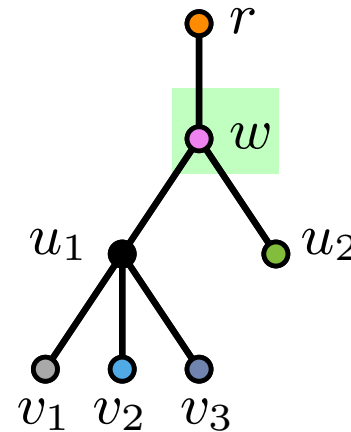
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



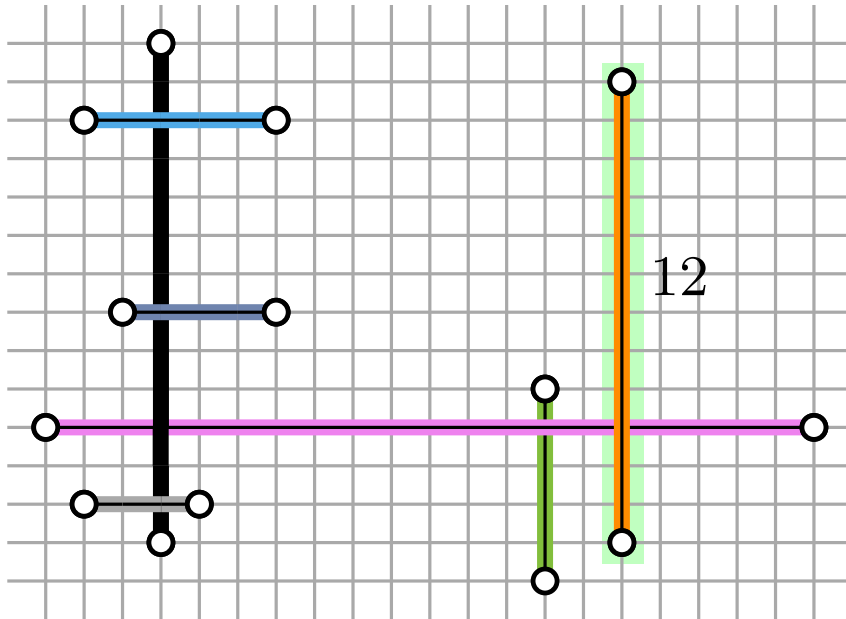
v_1 :	$T_0(v_1)$	=	3
	$T_1(v_1)$	=	2
v_2 :	$T_0(v_2)$	=	5
	$T_1(v_2)$	=	4
v_3 :	$T_0(v_3)$	=	4
	$T_1(v_3)$	=	2
u_1 :	$\text{short}(u_1) = T_3$	=	16
	$\text{long}(u_1) = T_4$	=	22
u_2 :	$T_0(u_2)$	=	5
	$T_1(u_2)$	=	2

$$\begin{aligned}
 T_0(w) &= l_0 + \text{short}(u_1) + \text{short}(u_2) &= 38 \\
 T_1(w) &= l_1 + \text{long}(u_1) + \text{long}(u_2) &= 33 \\
 w : \quad T_2(w) &= l_2 + \text{short}(u_1) + \text{long}(u_2) &= 31 \\
 T_3(w) &= l_3 + \text{short}(u_1) + \text{long}(u_2) &= 35
 \end{aligned}$$

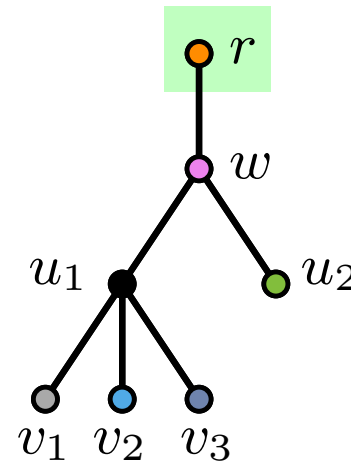
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



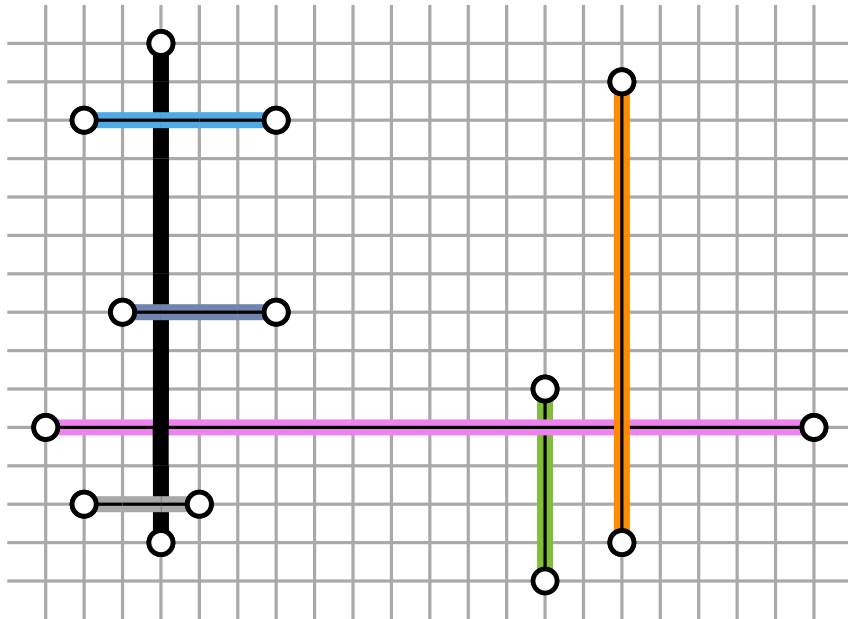
v_1	$T_0(v_1)$	=	3
	$T_1(v_1)$	=	2
v_2	$T_0(v_2)$	=	5
	$T_1(v_2)$	=	4
v_3	$T_0(v_3)$	=	4
	$T_1(v_3)$	=	2
u_1	$\text{short}(u_1) = T_3$	=	16
	$\text{long}(u_1) = T_4$	=	22
u_2	$T_0(u_2)$	=	5
	$T_1(u_2)$	=	2
w	$\text{short}(w) = T_1$	=	33
	$\text{long}(w) = T_0$	=	38

$$r : \begin{aligned} T_0(r) &= l_0 + \text{short}(w) &= 45 \\ T_1(r) &= l_1 + \text{long}(w) &= 44 \end{aligned}$$

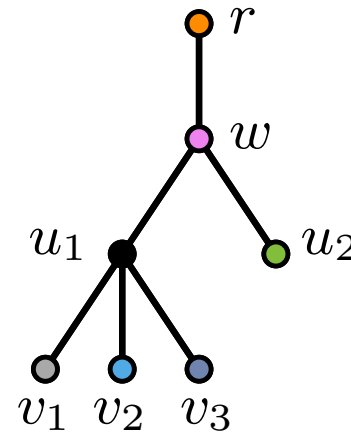
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



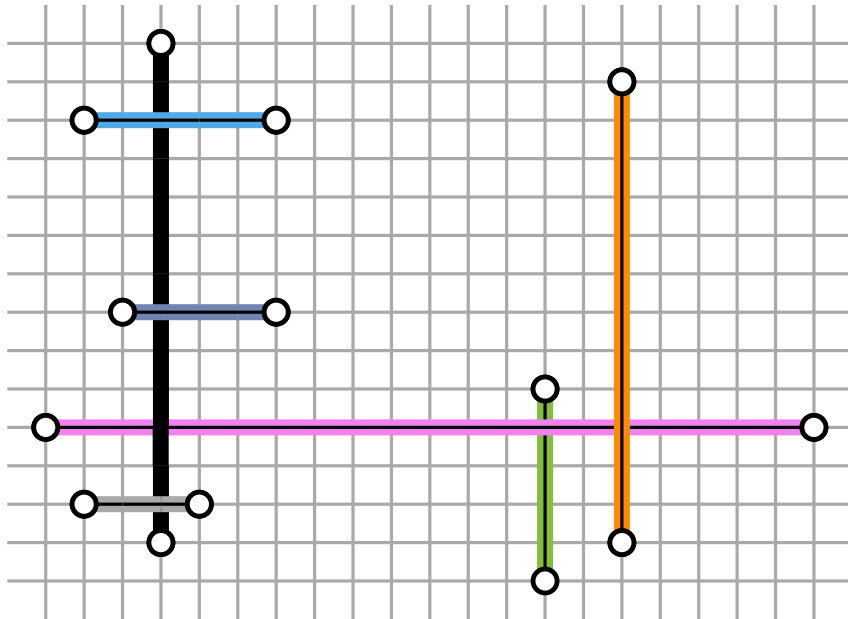
v_1	$T_0(v_1)$	=	3
	$T_1(v_1)$	=	2
v_2	$T_0(v_2)$	=	5
	$T_1(v_2)$	=	4
v_3	$T_0(v_3)$	=	4
	$T_1(v_3)$	=	2
u_1	$\text{short}(u_1) = T_3$	=	16
	$\text{long}(u_1) = T_4$	=	22
u_2	$T_0(u_2)$	=	5
	$T_1(u_2)$	=	2
w	$\text{short}(w) = T_1$	=	33
	$\text{long}(w) = T_0$	=	38

$$r : \begin{aligned} T_0(r) &= l_0 + \text{short}(w) &= & 45 \\ T_1(r) &= l_1 + \text{long}(w) &= & 44 \end{aligned}$$

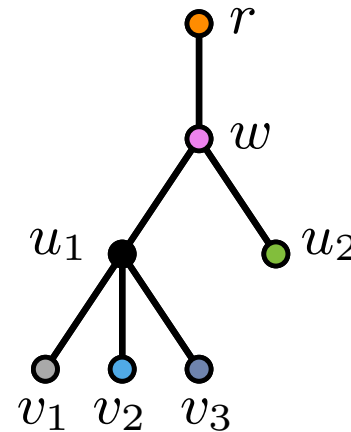
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

Input:



Intersection Graph:



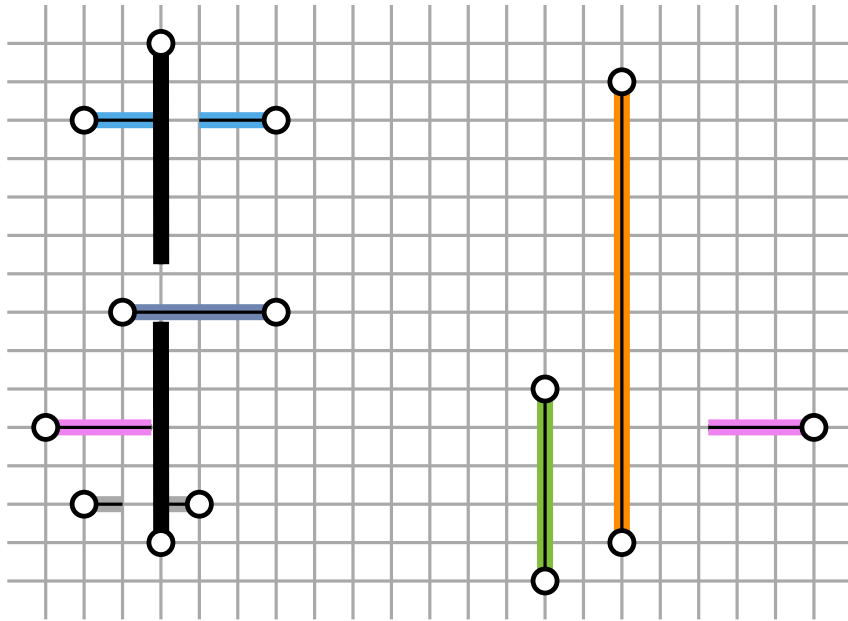
v_1	$T_0(v_1)$	=	3
	$T_1(v_1)$	=	2
v_2	$T_0(v_2)$	=	5
	$T_1(v_2)$	=	4
v_3	$T_0(v_3)$	=	4
	$T_1(v_3)$	=	2
u_1	$\text{short}(u_1) = T_3$	=	16
	$\text{long}(u_1) = T_4$	=	22
u_2	$T_0(u_2)$	=	5
	$T_1(u_2)$	=	2
w	$\text{short}(w) = T_1$	=	33
	$\text{long}(w) = T_0$	=	38

$$r : \begin{aligned} T_0(r) &= l_0 + \text{short}(w) &= 45 \\ T_1(r) &= l_1 + \text{long}(w) &= 44 \end{aligned} \quad \leftarrow \text{backtracking}$$

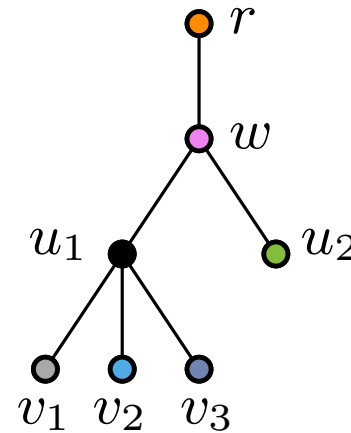
Dynamic Programming: Example

$$T_i(u) = l_i(u) + \sum_{v \in c(u)} \begin{cases} \text{short}(v) & \text{if } s(u) \text{ with length } l_i(u) \text{ intersects } s(v) \\ \text{long}(v) & \text{otherwise} \end{cases}$$

MaxSPED:



Intersection Graph:



v_1	$T_0(v_1)$	=	3
	$T_1(v_1)$	=	2
v_2	$T_0(v_2)$	=	5
	$T_1(v_2)$	=	4
v_3	$T_0(v_3)$	=	4
	$T_1(v_3)$	=	2
u_1	$\text{short}(u_1) = T_3$	=	16
	$\text{long}(u_1) = T_4$	=	22
u_2	$T_0(u_2)$	=	5
	$T_1(u_2)$	=	2
w	$\text{short}(w) = T_1$	=	33
	$\text{long}(w) = T_0$	=	38

$$r : \begin{aligned} T_0(r) &= l_0 + \text{short}(w) &= & 45 \\ T_1(r) &= l_1 + \text{long}(w) &= & 44 \end{aligned}$$

- recurrence can be solved naively in $O(mk^2)$ time for m segments in the k -plane input drawing Γ
- can be improved to $O(mk)$ time using dependencies in the order of the stub lengths
- intersection graph $C(\Gamma)$ is a tree with $O(m)$ edges and can be computed in $O(m \log m)$ time

- recurrence can be solved naively in $O(mk^2)$ time for m segments in the k -plane input drawing Γ
- can be improved to $O(mk)$ time using dependencies in the order of the stub lengths
- intersection graph $C(\Gamma)$ is a tree with $O(m)$ edges and can be computed in $O(m \log m)$ time

Theorem: MaxSPED can be solved in $O(mk + m \log m)$ time for a k -plane input drawing whose intersection graph is a tree.

- recurrence can be solved naively in $O(mk^2)$ time for m segments in the k -plane input drawing Γ
- can be improved to $O(mk)$ time using dependencies in the order of the stub lengths
- intersection graph $C(\Gamma)$ is a tree with $O(m)$ edges and can be computed in $O(m \log m)$ time

Theorem: MaxSPED can be solved in $O(mk + m \log m)$ time for a k -plane input drawing whose intersection graph is a tree.

MaxPED: similar algorithm idea, but non-symmetric stubs require k^2 pairs of stub lengths.

Theorem: MaxPED can be solved in $O(mk^2 + m \log m)$ time for k -plane input drawing with tree intersection graph.

If the edge intersection graph $C(\Gamma)$ has bounded treewidth τ then a more complex dynamic programming idea can be used.

- each node (bag) of a *nice* tree decomposition of C has at most $\tau + 1$ vertices; for a k -plane drawing Γ it is sufficient to store maximum ink values for at most $(k + 1)^{\tau+1}$ stub sets
- perform bottom-up dynamic programming in the nice tree decomposition, which has $O(\tau m)$ nodes
- the operations for one stub set require at most $O(k\tau)$ time

Bounded Treewidth

If the edge intersection graph $C(\Gamma)$ has bounded treewidth τ then a more complex dynamic programming idea can be used.

- each node (bag) of a *nice* tree decomposition of C has at most $\tau + 1$ vertices; for a k -plane drawing Γ it is sufficient to store maximum ink values for at most $(k + 1)^{\tau+1}$ stub sets
- perform bottom-up dynamic programming in the nice tree decomposition, which has $O(\tau m)$ nodes
- the operations for one stub set require at most $O(k\tau)$ time

Theorem: For a k -plane drawing Γ with m edges whose intersection graph has treewidth τ , MaxSPED can be solved in $O(m(k + 1)^{\tau+2}\tau^2 + m \log m)$ time.

Bounded Treewidth

If the edge intersection graph $C(\Gamma)$ has bounded treewidth τ then a more complex dynamic programming idea can be used.

- each node (bag) of a *nice* tree decomposition of C has at most $\tau + 1$ vertices; for a k -plane drawing Γ it is sufficient to store maximum ink values for at most $(k + 1)^{\tau+1}$ stub sets
- perform bottom-up dynamic programming in the nice tree decomposition, which has $O(\tau m)$ nodes
- the operations for one stub set require at most $O(k\tau)$ time

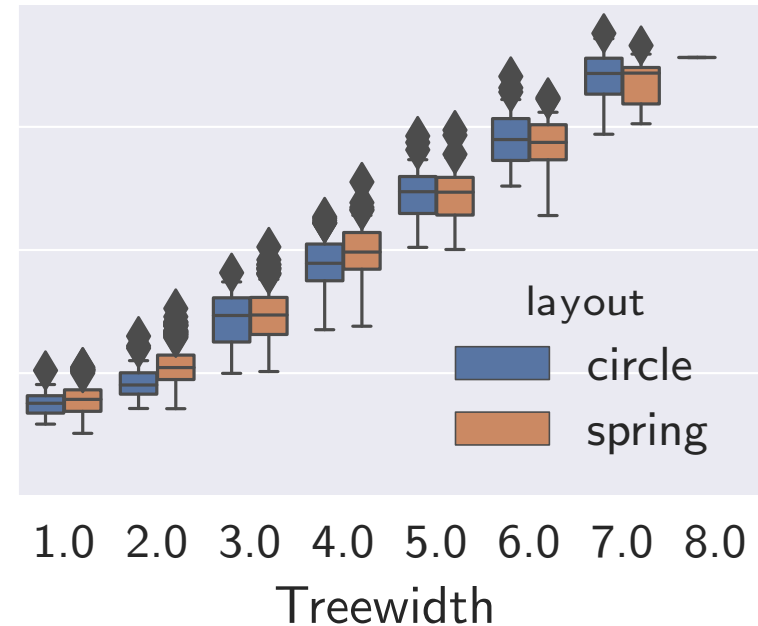
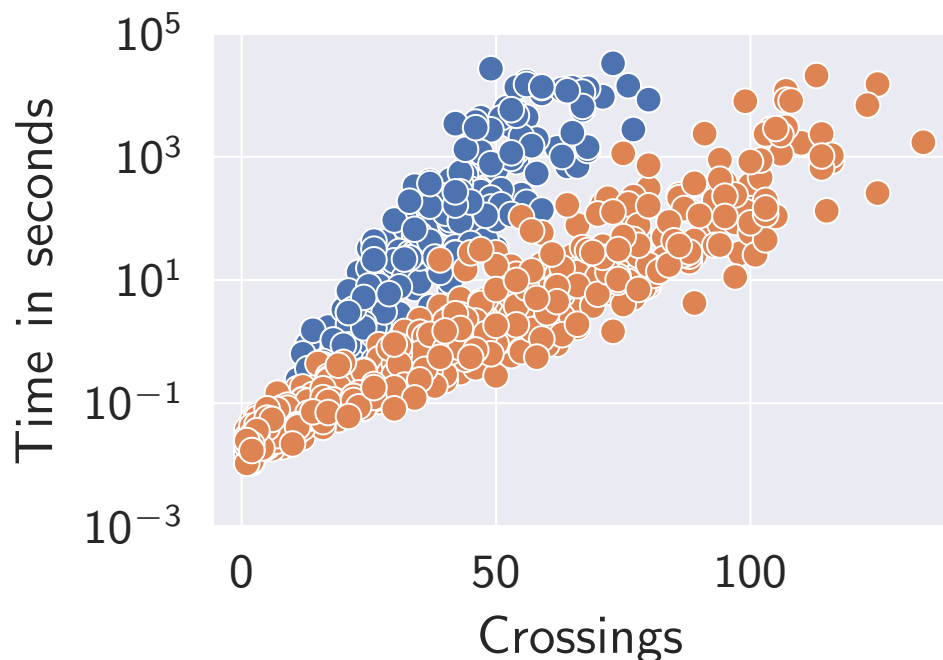
Theorem: For a k -plane drawing Γ with m edges whose intersection graph has treewidth τ , MaxSPED can be solved in $O(m(k + 1)^{\tau+2}\tau^2 + m \log m)$ time.

The algorithm can be adapted to solve MaxPED with an increase by a factor of k in the running time.

Experiments

We implemented the treewidth-based algorithms for MaxSPED in Python and performed some proof-of-concept experiments.

- used “htd” library to compute nice tree decomposition
- 800 random graphs with 40 vertices and 40–75 edges
- spring and circular layouts from NetworkX and graphviz



Conclusion

	$k = 2$	$k = 3$	$k \geq 4$	arbitrary k
MaxSPED		NP-hard		NP-hard [Bruckdorfer PhD'15]
MaxPED	$O(n \log n)$ [Bruckdorfer et al. JGAA'17]	Dynamic Programming if edge intersection graph <ul style="list-style-type: none"> is a tree, or more generally has bounded treewidth 		
			NP-hard	

	$k = 2$	$k = 3$	$k \geq 4$	arbitrary k
MaxSPED		NP-hard		NP-hard [Bruckdorfer PhD'15]
MaxPED	$O(n \log n)$ [Bruckdorfer et al. JGAA'17]	Dynamic Programming if edge intersection graph <ul style="list-style-type: none"> is a tree, or more generally has bounded treewidth 		
		?	NP-hard	

open questions:

- complexity of MaxPED for $k = 3$
- algorithms/complexity for deciding existence of δ -HPEDs

	$k = 2$	$k = 3$	$k \geq 4$	arbitrary k
MaxSPED		NP-hard		NP-hard [Bruckdorfer PhD'15]
MaxPED	$O(n \log n)$ [Bruckdorfer et al. JGAA'17]	Dynamic Programming if edge intersection graph <ul style="list-style-type: none"> is a tree, or more generally has bounded treewidth 		
		?	NP-hard	

open questions:

- complexity of MaxPED for $k = 3$
- algorithms/complexity for deciding existence of δ -HPEDs

Thank You!